## Terramechanics

- Origin and nature of lunar soil
- Soil mechanics
- Rigid wheel mechanics


## Effect of Lateral Velocity at Touchdown

- Resolve torques around landing gear footpad


$$
\begin{aligned}
\ddot{\theta} & =\frac{\tau_{t o t}}{I_{t o t}} \\
\ddot{\theta} & =\frac{F_{h} h-F_{v} w-m g w}{I_{c g}+m \ell^{2}}
\end{aligned}
$$

- Worst cases - hit obstacle (high force), landing downhill
- Issue: rotational velocity induced is counteracted by vehicle weight
- Will vehicle rotation stop before overturn limit?


## Simple Approach to Landing Stability



Kinetic energy at landing

$$
K . E .=\frac{1}{2} m v^{2}=\frac{1}{2} m\left(v_{v}^{2}+v_{h}^{2}\right)
$$

Worst case: assume $v_{v}^{2}=0$
Dissipated by potential energy of raising C.G. by rotation around impact point

$$
\begin{gathered}
\text { P.E. }=m g \Delta h=m g(\ell-h) \\
v_{c r i t}=\sqrt{2 g(\ell-h)} \quad \text { or } \quad w_{r e q}=\sqrt{\left(\frac{v_{h}^{2}}{2 g}+h\right)^{2}-h^{2}}
\end{gathered}
$$

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## Worst Case: Downhill Landing



Kinetic energy at landing

$$
K . E .=\frac{1}{2} m v^{2}=\frac{1}{2} m\left(v_{v}^{2}+v_{h}^{2}\right)
$$

Both $v_{h}$ and $v_{v}$ can drive overturn

$$
P . E .=m g \Delta h=m g[\ell-(w \sin \gamma+h \cos \gamma)]
$$

$$
v_{c r i t}=\sqrt{\frac{g}{2}[\ell-(w \sin \gamma+h \cos \gamma)]}
$$

## Lunar Regolith

- Broken down from larger pieces over time
- Major constituents
- Rock fragments
- Mineral fragments
- Glassy particles
- Local environment
$-10^{-12}$ torr ( $\left.=1.22 \times 10^{-10} \mathrm{~Pa}=1.93 \times 10^{-14} \mathrm{psi}\right)$
- Meteorites at velocities $>10^{5} \mathrm{~m} / \mathrm{sec}$
- Galactic cosmic rays, solar particles
- Temperature range $+250^{\circ} \mathrm{F}--250^{\circ} \mathrm{F}$


## Regolith Creation Process

- Only "weathering" phenomenon on the moon is meteoritic impact!
- Weathering processes
- Comminution: breaking rocks and minerals into smaller particles
- Agglutination: welding fragments together with molten glass formed by impact energy
- Solar wind spallation and implantation (miniscule)
- Fire fountaining (dormant)


## JSC-1 Simulant

- Ash vented from Merriam Crater in San Francisco volcano field near Flagstaff, AZ
- K-Ar dated at 150,000 years old $\pm 30,000$
- Major constituents $\mathrm{SiO}_{2}, \mathrm{TiO}_{2}, \mathrm{Al}_{2} \mathrm{O}_{3}, \mathrm{Fe}_{2} \mathrm{O}_{3}, \mathrm{FeO}$, $\mathrm{MgO}, \mathrm{CaO}, \mathrm{Na}_{2} \mathrm{O}$, other $<1 \%$
- Represents low-Ti regolith from lunar mare
- MLS-1 simulant (U.Minn.) preferred for simulation of highland material
- BP-1 (Flagstaff, AZ) is ground basaltic lava higher fidelity because of angular grain shapes


## Wheel-Soil Interaction

## Wheel rolling over soil does work <br> - Compression <br> - "Bulldozing"


from Gibbesch and Schafer, "Advanced and Simulation Methods of Planetary Rover Mobility on Soft Terrain" 8th ESA Workshop
on Advanced Space Technologies for Robotics and Automation, Noordwijk, The Netherlands, November, 2004

## Soil Testing Apparatus



Bevameter (force vs. displacement)


Internal friction angle $\varphi$


Shear deformation modulus $\mathbf{K}$

Terramechanics

## Soil Characterization - Direct Shear



## Modeling Soil Reaction to a Wheel

Assume soil reaction is like a (nonlinear) spring

$$
P=k z^{n}
$$

$$
P=\text { applied pressure }
$$

$$
z=\text { compression depth }
$$

$k, n=$ heuristic parameters


## Effects of Soil Mechanics



## Wheel-Soil Interactions



Displacement Energy $\frac{E}{A}=\int \frac{F}{A} d z=\int P d z$

$$
\frac{E}{A}=\int_{0}^{z_{o}} P d z=\int_{0}^{z_{o}} k z^{n} d z=k \frac{z_{o}^{n+1}}{n+1}
$$

## Rolling Resistance

$$
\text { Total Energy } \frac{E}{A} A=\frac{E}{A} b d=k \frac{z_{o}^{n+1}}{n+1} b d
$$

Given a force resisting rolling $\equiv R$,
the energy required to roll a distance d is

$$
\begin{gathered}
E_{\text {roll }}=R d \\
E_{\text {roll }}=E_{\text {displacement }} \Rightarrow R d=\frac{E}{A} b d
\end{gathered}
$$

## Rolling Resistance

$$
\text { For } n=1: P=k z ; \frac{E}{A}=k \frac{z_{o}^{2}}{2} ; R=\frac{1}{2} k b z_{o}^{2}
$$

$$
\text { For } n=\frac{1}{2}: P^{2}=k^{2} z ; \frac{E}{A}=\frac{2}{3} k z_{o}^{\frac{3}{2}} ; R=\frac{2}{3} k b z_{o}^{\frac{3}{2}}
$$

$$
\text { For } n=0: P=k ; \frac{E}{A}=k z_{o} ; R=k b z_{o}
$$

Generic case: $P=k z^{n} ; \frac{E}{A}=k \frac{z_{o}^{n+1}}{n+1} ; R=k b \frac{z_{o}^{n+1}}{n+1}$

## Soil Displacement Calculations



$$
\begin{aligned}
& R-\int_{0}^{\theta_{o}} d F \sin \theta=0 \\
& -W+\int_{0}^{\theta_{o}} d F \cos \theta=0
\end{aligned}
$$

$$
d F \cos \theta=-P b d x
$$

$$
d F=P b r d \epsilon \quad d F \cos \theta=-P b d x
$$

$$
R=\int_{0}^{\theta_{o}} P b d z \quad W=-\int_{0}^{\theta_{o}} P b d x
$$

In general, $P=k x^{n}$

$$
W=-\int_{0}^{z_{o}} b k z^{n} d x
$$

## Soil Displacement Calculations

$$
\begin{aligned}
& \text { wheel width } b \\
& x^{2}=\left(\frac{D}{2}\right)^{2}-\overline{A B}=\frac{D}{2}-\left(z_{o}-z\right) \\
& =\left(\frac{D}{2}\right)^{2}-\left(\frac{D}{2}\right)^{2}-\left[\frac{D}{2}-\left(z_{o}-z\right)\right]^{2}+2 \frac{D}{2}\left(z_{o}-z\right)-\left(z_{o}-z\right)^{2} \\
& x^{2}=\left[D-\left(z_{o}-z\right)\right]\left(z_{o}-z\right)
\end{aligned}
$$

## Soil Compression Calculations

But $D \gg z_{o}-z$

$$
x^{2} \approx D\left(z_{o}-z\right) \Rightarrow 2 x d x=-D d z
$$

so from $W=-\int_{0}^{z_{o}} b k z^{n} d x$ we get $W=-\int_{0}^{z_{o}} b k z^{n} \frac{-D}{2 x} d z$

$$
\begin{gathered}
W=-b k \int_{0}^{z_{o}} z^{n}\left(\frac{-D}{2 \sqrt{D} \sqrt{z_{o}-z}}\right) d z \\
W=b k \int_{0}^{z_{o}} z^{n}\left(\frac{\sqrt{D} d z}{2 \sqrt{z_{o}-z}}\right) d z
\end{gathered}
$$

## Soil Displacement Calculations

$$
\begin{aligned}
& \text { Define } z_{o}-z \equiv t^{2} \Rightarrow d z=-2 t d t \\
& \qquad W=b k \sqrt{D} \int_{0}^{\sqrt{z_{o}}}\left(z_{o}-t^{2}\right)^{n} d t
\end{aligned}
$$

Taylor Series expansion $\left(z_{o}-t^{2}\right)^{n} \cong z_{o}^{n}-n z_{o}^{n-1} t^{2}+\cdots$

$$
\begin{gathered}
W \approx \frac{b k \sqrt{D z_{o}}}{3} z_{o}^{n}(3-n) \\
\text { for } n=1 \Rightarrow W=\frac{2}{3} b k z_{o} \sqrt{D z_{o}} \\
\text { for } n=\frac{1}{2} \Rightarrow W=\frac{5}{6} b k z_{o} \sqrt{D} \\
\text { for } n=0 \Rightarrow W=b k \sqrt{D z_{o}}
\end{gathered}
$$

## Rolling Resistance as $f(\mathbf{W})$

$$
\begin{gathered}
\text { for } n=0 \Rightarrow W=b k \sqrt{D z_{o}} \Rightarrow z_{o}=\left(\frac{W}{b k}\right)^{2} \frac{1}{D} \\
\qquad R=k b z_{o} \Rightarrow R=\frac{k b}{(k b)^{2}} \frac{W^{2}}{D} \Rightarrow R=\frac{W^{2}}{k b D} \\
\text { for } n=\frac{1}{2} \Rightarrow W=\frac{5}{6} b k z_{o} \sqrt{D} \Rightarrow z_{o}=\frac{6}{5} \frac{W}{b k \sqrt{D}} \\
R=\frac{2}{3} k b z_{o}^{\frac{3}{2}} \Rightarrow R=\frac{2}{3} k b\left(\frac{6}{5} \frac{W}{k b \sqrt{D}}\right)^{\frac{3}{2}}=\frac{2}{3}\left(\frac{6}{5}\right)^{\frac{3}{2}} \frac{W^{\frac{3}{2}}}{\sqrt{k b} D^{\frac{3}{4}}} \\
R=0.876 \frac{W^{\frac{3}{2}}}{\sqrt{k b} D^{\frac{3}{4}}}
\end{gathered}
$$

## Rolling Resistance as $f(\mathbf{W})$

$$
\begin{gathered}
\text { for } n=1 \Rightarrow W=\frac{2}{3} b k z_{o}^{\frac{3}{2}} \sqrt{D} \Rightarrow z_{o}^{2}=\left(\frac{3 W}{2 k b \sqrt{D}}\right)^{\frac{4}{3}} \\
R=\frac{1}{2} k b z_{o}^{2} \Rightarrow R=\frac{1}{2} k b\left(\frac{3 W}{2 k b \sqrt{D}}\right)^{\frac{4}{3}}=\frac{1}{2}\left(\frac{3}{2}\right)^{\frac{4}{3}}\left(\frac{W^{4}}{k b D^{2}}\right)^{\frac{1}{3}} \\
R=0.859\left(\frac{W^{4}}{k b D^{2}}\right)^{\frac{1}{3}}
\end{gathered}
$$

## Rolling Resistance as $f(W)$ (Generic)

$$
\begin{gathered}
W=\frac{b k \sqrt{D z_{o}}}{3} z_{o}^{n}(3-n)=\frac{b k \sqrt{D}}{3} z_{o}^{n+\frac{1}{2}}(3-n) \\
z_{o}^{n+\frac{1}{2}}=\frac{3}{(3-n)} \frac{W}{b k \sqrt{D}} \\
z_{o}^{n+1}=\left(\frac{3}{3-n} \frac{W}{b k \sqrt{D}}\right)^{\frac{n+1}{n+\frac{1}{2}}}=\left(\frac{3}{3-n} \frac{W}{b k \sqrt{D}}\right)^{\frac{2(n+1)}{2 n+1}} \\
R=\frac{b k}{n+1} z_{o}^{n+1}=\frac{b k}{n+1}\left(\frac{3}{3-n} \frac{W}{b k \sqrt{D}}\right)^{\frac{2(n+1)}{2 n+1}} \\
R=\frac{1}{n+1}\left(\frac{3}{3-n} \frac{W}{\sqrt{D}}\right)^{\frac{2(n+1)}{2 n+1}}\left(\frac{1}{b k}\right)^{\frac{1}{2 n+1}}
\end{gathered}
$$

## More Detailed Soil Compression Equation

$$
k=\frac{k_{c}}{b}+k_{\phi}
$$

$k_{c}=$ modulus of cohesion of soil deformation

$$
k_{c} \text { units } \Rightarrow<N / m^{(n+1)}>
$$

$k_{\phi}=$ modulus of friction of soil deformation

$$
\begin{gathered}
k_{\phi} \text { units } \Rightarrow<N / m^{(n+2)}> \\
b=\text { wheel width }
\end{gathered}
$$

$$
P=\left(\frac{k_{c}}{b}+k_{\phi}\right) z^{n}
$$

## Soil Characteristics

| soil type | n | $k_{c}\left\langle\frac{N}{m^{n+1}}\right\rangle$ | $k_{\phi}\left\langle\frac{N}{m^{n+2}}\right\rangle$ |
| :---: | :---: | ---: | ---: |
| Dry Sand | 1.1 | 990 | $1,528,000$ |
| Lunar Regolith | 1 | 1400 | 820,000 |
| Sandy Loam | 0.7 | 5270 | $1,515,000$ |
| Sandy Loam <br> (MER-B) | 1 | 28,000 | $7,600,000$ |
| Slope Soil <br> (MER-B) | 0.8 | 6800 | 210,000 |
| Clay (Earth) | 0.5 | 13,190 | 692,200 |

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## Equations for Compression Resistance

$$
\begin{gathered}
z=\left(\frac{3 W_{w}}{(3-n) b k \sqrt{d}}\right)^{\frac{2}{2 n+1}} \\
W_{w}=\text { weight on wheel } \\
d=\text { wheel diameter }
\end{gathered}
$$

$$
R_{c}=\left(\frac{b k}{n+1}\right) z^{n+1}
$$

$R_{c}=$ compression resistance (per wheel)

## Soil Compression - Reece Formulation



Problem is that $k_{c}$ and $k_{\phi}$ have variable dimensions, based on $n$
$k_{c}$ units $\Rightarrow<N / m^{(n+1)}>$
$k_{\phi}$ units $\Rightarrow<N / m^{(n+2)}>$

## Compression Resistance (Lunar Soil)

$$
\begin{gathered}
R_{c}=\frac{1}{n+1}\left(k_{c}+b k_{\phi}\right)^{\frac{-1}{2 n+1}}\left(\frac{3 W_{w}}{(3-n) \sqrt{d}}\right)^{\frac{2(n+1)}{2 n+1}} \\
n=1 \\
k_{c}=0.14 \mathrm{~N} / \mathrm{cm}^{2} \\
k_{\phi}=0.827 \mathrm{~N} / \mathrm{cm}^{3} \\
R_{c}=\frac{1}{2}\left(k_{c}+b k_{\phi}\right)^{\frac{-1}{3}}\left(\frac{3 W_{w}}{2 \sqrt{d}}\right)^{\frac{4}{3}}
\end{gathered}
$$

## Apollo Lunar Roving Vehicle Example

$$
\begin{gathered}
z=\left(\frac{3 * 253}{2(0.14+17.4 * 0.827) \sqrt{82}}\right)^{\frac{2}{3}}=2.03 \mathrm{~cm} \\
R_{c}=\frac{1}{2}(0.14+17.4 * 0.827)^{\frac{-1}{3}}\left(\frac{3 * 253}{2 \sqrt{82}}\right)^{\frac{4}{3}}=29.8 \mathrm{~N}
\end{gathered}
$$

check units -

$$
\left(\frac{N^{-1 / 3}}{c m^{-2 / 3}}\right)\left(\frac{N^{4 / 3}}{c m^{2 / 3}}\right)=N
$$

## Rolling and Gravitation Resistance

- Rolling resistance (tires, bearings, etc.)

$$
\begin{gathered}
R_{r}=W_{v} c_{f} \\
W_{v}=\text { weight of vehicle } \\
c_{f}=\text { coefficient of friction (typ. } 0.05 \text { ) }
\end{gathered}
$$

- Gravitational resistance

$$
R_{g}=W_{v} \sin \theta_{\text {slope }}
$$

- LRV examples ( $15^{\circ}$ slope)

$$
R_{r}=51 N \quad R_{g}=262 N
$$

## Bulldozing Resistance

- "Bulldozing" is the process of pushing soil up ahead of the wheel
- Ranges from a small factor to a huge one, depending on soil and wheel factors
- Will be covered in detail in a later lecture


## Example: Wheelbarrow (Single) Wheel

$$
R=\left(k_{c}+k_{\phi} b\right)^{\frac{-1}{2 n+1}} W^{\frac{2(n+1)}{2 n+1}} \frac{1}{n+1}\left(\frac{3}{3-n}\right)^{\frac{2(n+1)}{2 n+1}} D^{\frac{-(n+1)}{2 n+1}}
$$



## Effects of Wheel Parameters



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## Effect of Soil "Spring Constant" on R/W



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## Soil Type and Wheel Load



## Soil Type and Specific Resistance



## Effect of Wheel Diameter and Width



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## Effect of Slope



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