

From last time,

$$\frac{dV}{dt} = \left(\frac{V^2}{r} - g\right) \sin \gamma - \frac{D}{m}$$

$$V \frac{d\gamma}{dt} = \frac{L}{m} + \left(\frac{V^2}{r} - g\right) \cos \gamma$$

Assume (at entry velocities close to orbital) $g \approx \frac{V^2}{r}$

Equations of motion become

$$V \frac{d\gamma}{dt} = \frac{L}{m} = \frac{\rho V^2}{2} \frac{C_L A}{m} = \frac{\rho V^2}{2\beta} \left(\frac{L}{D}\right) \quad (1)$$

$$\frac{dV}{dt} = -\frac{D}{m} = -\frac{\rho V^2}{2\beta} \quad (2)$$

Divide (2) by (1)

$$\frac{\frac{dV}{dt}}{V \frac{d\gamma}{dt}} = \frac{-\frac{\rho V^2}{2\beta}}{\frac{\rho V^2 L}{2\beta D}} \Rightarrow \frac{dV}{V} = -\frac{d\gamma}{L/D} \quad (3)$$

$$\int_{V_e}^V \frac{dV}{V} = -\frac{1}{L/D} \int_{\gamma_e}^{\gamma} d\gamma$$

$$\ln \frac{V}{V_e} = \frac{-(\gamma - \gamma_e)}{L/D} \Rightarrow \frac{V}{V_e} = e^{-\frac{\gamma - \gamma_e}{L/D}} \quad (4)$$

As before, $\frac{dh}{dt} = V \sin \gamma$ (5) $\rho = \rho_0 e^{-h/h_s}$ (6)

$$\frac{d\rho}{dt} = -\frac{\rho_0}{h_s} e^{-h/h_s} \frac{dh}{dt} = -\frac{\rho}{h_s} \frac{dh}{dt} \Rightarrow \frac{d\rho}{dt} = -\frac{\rho}{h_s} V \sin \gamma \quad (7)$$

Solve for V $V = \frac{-h_s}{\sin \gamma} \left(\frac{1}{\rho} \frac{d\rho}{dt}\right)$ (8)

Substitute (8) \Rightarrow (1) which we rewrite as

$$\frac{d\gamma}{dt} = \frac{\rho V}{2\beta} \left(\frac{L}{D}\right) = \frac{\rho}{2\beta} \frac{L}{D} \left(\frac{-h_s}{\sin \gamma}\right) \frac{1}{\rho} \frac{d\rho}{dt}$$

$$d\gamma = -\frac{h_s}{2\beta \sin\gamma} \frac{L}{D} d\rho \quad (9)$$

$$\int_{\gamma_e}^{\gamma} \sin\gamma d\gamma = -\frac{h_s}{2\beta} \frac{L}{D} \int_0^{\rho} d\rho \quad (10)$$

$$\cos\gamma - \cos\gamma_e = +\frac{h_s}{2\beta} \frac{L}{D} \rho \quad (11)$$

[$\int \sin = -\cos$]

$$\cos\gamma = \frac{h_s}{2\beta} \frac{L}{D} \rho + \cos\gamma_e$$

$$\gamma = \cos^{-1}\left(\frac{h_s}{2\beta} \frac{L}{D} \rho + \cos\gamma_e\right) \quad (12)$$

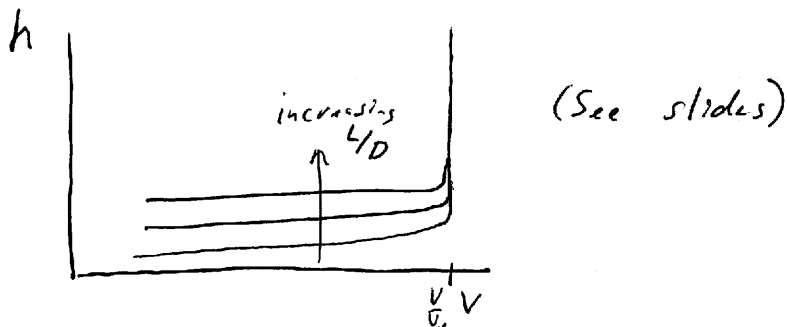
We add a negative sign because the flight path angle is negative, and \cos^{-1} is ambiguous about direction.

~~cos is ambiguous in terms of direction - we know flight path angle will be negative~~

$$\gamma = \cos^{-1}\left(\frac{h_s}{2\beta} \frac{L}{D} \rho_0 e^{-h/h_s} + \cos\gamma_e\right) \quad (13)$$

Rewrite (4) as $V = V_e \exp\left[-\frac{\gamma - \gamma_e}{L/D}\right] = V_e \exp\left[\frac{\gamma_e - \gamma}{L/D}\right]$
and substitute in (13)

$$V = V_e \exp\left\{\frac{L}{D} \left[\gamma_e + \cos^{-1}\left(\frac{h_s}{2\beta} \frac{L}{D} \rho_0 e^{-h/h_s} + \cos\gamma_e\right)\right]\right\} \quad (14)$$



Find peak deceleration

- along flight path $\left|\frac{D}{m}\right| = \frac{\rho V^2}{2\beta}$

- perpendicular to flight path $\left|\frac{L}{m}\right| = \frac{\rho V^2}{2\beta} \left(\frac{L}{D}\right)$

(worried only about magnitude)

Total deceleration

$$n = \sqrt{\left(\frac{D}{m}\right)^2 + \left(\frac{L}{m}\right)^2} = \frac{1}{m} \sqrt{D^2 + L^2} = \sqrt{\frac{\rho_0 V^2}{2\beta} \left(1 + \left(\frac{L}{D}\right)^2\right)}$$

$$\boxed{n = \frac{\rho_0 V^2}{2\beta} \sqrt{1 + \left(\frac{L}{D}\right)^2} e^{-h/h_s}} \quad (15)$$

Plug (14) into (15), but first rewrite (15) as

$$n = \frac{\rho_0}{2\beta} \sqrt{1 + \left(\frac{L}{D}\right)^2} e^{-h/h_s} V^2$$

$$n = \frac{\rho_0 V^2}{2\beta} \sqrt{1 + \left(\frac{L}{D}\right)^2} e^{-h/h_s} \exp\left\{\frac{2}{4D} \left[\gamma_e + \cos^{-1}\left(\frac{h_s}{2\beta} \frac{L}{D} \rho_0 e^{-h/h_s} + \cos \gamma_e\right)\right]\right\}$$

from $\{ \}^2$

Let the quantity in $[] = X$

$$n = \frac{\rho_0 V_e^2}{2\beta} \sqrt{1 + \left(\frac{L}{D}\right)^2} e^{-h/h_s} e^{\frac{2X}{4D}} \quad (16)$$

and

$$X = \gamma_e + \cos^{-1}\left(\frac{h_s}{2\beta} \frac{L}{D} \rho_0 e^{-h/h_s} + \cos \gamma_e\right) \quad (17)$$

$$\text{set } \frac{dn}{dh} = 0$$

$$0 = \frac{\rho_0 V_e^2}{2\beta} \sqrt{1 + \left(\frac{L}{D}\right)^2} \left[e^{-h/h_s} e^{\frac{2X}{4D}} \frac{2}{4D} \frac{dX}{dh} + \left(\frac{-1}{h_s}\right) e^{-h/h_s} e^{\frac{2X}{4D}} \right] \quad (18)$$

Factoring out common terms

$$\frac{1}{h_s} = \frac{2}{4D} \frac{dX_m}{dh} \quad (19)$$

From (13),

$$\delta = -\cos^{-1}\left(\frac{hs}{2\beta} \frac{L}{D} \rho_0 e^{-h/hs} + \cos \delta_e\right)$$

$$X = \delta_e - \delta$$

$$= -\cos^{-1}[\cos \delta] + \delta_e \quad \text{let } Y = \cos \delta$$

$$X = \delta_e - \cos^{-1} Y \quad (20)$$

$$\text{Trig identity: } \frac{d(\cos^{-1} u)}{dx} = \frac{-1}{\sqrt{1-u^2}} \frac{du}{dx} \quad (21)$$

$$\frac{dX}{dh} = - \frac{d(\cos^{-1} Y)}{dh} = \frac{+1}{\sqrt{1-Y^2}} \frac{dY}{dh}$$

$$= \frac{1}{\sqrt{1-Y^2}} \frac{d(\cos \delta)}{dh}$$

$$\text{From (13), } \frac{dX}{dh} = \frac{1}{\sqrt{1-(\cos \delta)^2}} \frac{d}{dh} \left[\frac{hs\rho_0 L}{2\beta D} e^{-h/hs} + \cos \delta_e \right] \quad (22)$$

$$= \frac{1}{\sqrt{1-\cos^2 \delta}} \left[\frac{L}{D} \frac{hs\rho_0}{2\beta} \left(-\frac{1}{hs}\right) e^{-h/hs} \right]$$

$$\frac{dX}{dh} = \frac{-\rho_0}{2\beta \sin \delta} \frac{L}{D} e^{-h/hs} \quad (23)$$

If we go back to n_{\max} case, (19) gives

$$\frac{1}{hs} = \frac{2}{4\beta} \frac{-\rho_0}{2\beta \sin \delta_m} \frac{L}{D} e^{-h_{\max}/hs} \quad (24) \quad h_m, \delta_m = \text{at } n_{\max}$$

$$\sin \delta_m = \frac{-hs\rho_0}{\beta} e^{-h_m/hs} \quad (25)$$

$$\cos \delta_m = \frac{4 \cos \delta_e \pm \sqrt{16 \cos^2 \delta_e + [4 + (\frac{L}{D})^2] (\frac{L}{D})^2}}{4 + (\frac{L}{D})^2}$$

$$\cos \delta = \frac{h_s}{2\beta} \frac{L}{D} \rho_0 e^{-h/L_s} + \cos \delta_e \quad \frac{L}{D} = 0 \Rightarrow \cos \delta = \cos \delta_e$$

$$(25) \text{ sinus} \quad \sin \delta_m = \frac{-h_s \rho_0}{\beta} e^{-h/L_s} \quad e^{-h/L_s} = \frac{-\beta \sin \delta_m}{h_s \rho_0}$$

$$\cos \delta - \cos \delta_e = \frac{h_s}{2\beta} \frac{L}{D} \rho_0 e^{-h/L_s}$$

$$\cos \delta_m - \cos \delta_e = -\frac{h_s}{2\beta} \frac{L}{D} \rho_0 \frac{\beta \sin \delta_m}{h_s \rho_0}$$

$$\cos \delta_m - \cos \delta_e = -\frac{1}{2} \frac{L}{D} \sin \delta_m$$

$$(\cos \delta_m - \cos \delta_e)^2 = \frac{1}{4} \left(\frac{L}{D}\right)^2 \sin^2 \delta_m$$

$$4(\cos^2 \delta_m - 2 \cos \delta_m \cos \delta_e + \cos^2 \delta_e) = \left(\frac{L}{D}\right)^2 (1 - \cos^2 \delta_m) \\ = \left(\frac{L}{D}\right)^2 - \left(\frac{L}{D}\right)^2 \cos^2 \delta_m$$

$$\left[4 + \left(\frac{L}{D}\right)^2\right] \cos^2 \delta_m - [8 \cos \delta_e] \cos \delta_m + [4 \cos^2 \delta_e - \left(\frac{L}{D}\right)^2] = 0$$

$$\cos \delta_m = \frac{8 \cos \delta_e \pm \sqrt{64 \cos^2 \delta_e - 4[4 + (\frac{L}{D})^2][4 \cos^2 \delta_e - (\frac{L}{D})^2]}}{2[4 + (\frac{L}{D})^2]}$$

$$= \frac{4 \cos \delta_e \pm \sqrt{16 \cos^2 \delta_e - [4 + (\frac{L}{D})^2][4 \cos^2 \delta_e - (\frac{L}{D})^2]}}{4 + (\frac{L}{D})^2}$$

$$= \frac{4}{4 + (\frac{L}{D})^2} \cos \delta_e + \frac{1}{4 + (\frac{L}{D})^2} \sqrt{16 \cos^2 \delta_e - [6 \cos^2 \delta_e - 4(\frac{L}{D})^2 + 4 \cos^2 \delta_e (\frac{L}{D})^2 - (\frac{L}{D})^4]}$$

$$= \frac{1}{4 + (\frac{L}{D})^2} \left\{ 4 \cos \delta_e + \sqrt{4(\frac{L}{D})^2 - 4 \cos^2 \delta_e (\frac{L}{D})^2 + (\frac{L}{D})^4} \right\}$$

$$= \frac{1}{4 + (\frac{L}{D})^2} \left[4 \cos \delta_e + \frac{L}{D} \sqrt{4 - 4 \cos^2 \delta_e + (\frac{L}{D})^2} \right]$$

$$\cos \delta_m = \frac{4 \cos \delta_e + \frac{L}{D} \sqrt{4 \sin^2 \delta_e + \left(\frac{L}{D}\right)^2}}{4 + \left(\frac{L}{D}\right)^2}$$

$$\frac{L}{D} = 0 \quad \delta_m = \delta_e \quad \checkmark$$

$$e^{-h_m/h_s} = \frac{-\beta \sin \delta_m}{h_s \rho_0}$$

$$= -\frac{\beta}{h_s \rho_0} \left\{ 1 - \left[\frac{4 \cos \delta_e + \frac{L}{D} \sqrt{4 \sin^2 \delta_e + \left(\frac{L}{D}\right)^2}}{4 + \left(\frac{L}{D}\right)^2} \right]^2 \right\}^{1/2}$$

$$\hookrightarrow V_m, \quad n_m$$

$$V_m = V_e e^{-\frac{(\delta_m - \delta_e)}{L/D}}$$

$$n_m = \frac{\rho_0 V_m^2}{2\beta} \sqrt{1 + \left(\frac{L}{D}\right)^2} e^{-h_m/h_s}$$