

# Course Overview/Orbital Mechanics

- Course Overview
  - Challenges of launch and entry
  - Course goals
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  - Syllabus
  - Policies
  - Project Content
- An overview of orbital mechanics at “point five past lightspeed”

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**Course Overview; Orbital Mechanics**  
**ENAE 791 - Launch and Entry Vehicle Design**

# Space Launch - The Physics

- Minimum orbital altitude is  $\sim 200$  km

$$\frac{\text{Potential Energy}}{\text{kg in orbit}} = -\frac{\mu}{r_{orbit}} + \frac{\mu}{r_E} = 1.9 \times 10^6 \frac{J}{kg}$$

- Circular orbital velocity there is 7784 m/sec

$$\frac{\text{Kinetic Energy}}{\text{kg in orbit}} = \frac{1}{2} \frac{\mu}{r_{orbit}^2} = 30 \times 10^6 \frac{J}{kg}$$

- Total energy per kg in orbit

$$\frac{\text{Total Energy}}{\text{kg in orbit}} = KE + PE = 32 \times 10^6 \frac{J}{kg}$$



# Theoretical Cost to Orbit

- Convert to usual energy units

$$\frac{\text{Total Energy}}{\text{kg in orbit}} = 32 \times 10^6 \frac{\text{J}}{\text{kg}} = 8.9 \frac{\text{kWhrs}}{\text{kg}}$$

- Domestic energy costs are  $\sim \$0.05/\text{kWhr}$

▶▶ Theoretical cost to orbit  $\$0.44/\text{kg}$



# Actual Cost to Orbit



- Delta IV Heavy
  - 23,000 kg to LEO
  - \$250 M per flight
- \$10,870/kg of payload
- Factor of 25,000x higher than theoretical energy costs!



# What About Airplanes?

- For an aircraft in level flight,

$$\frac{\text{Weight}}{\text{Thrust}} = \frac{\text{Lift}}{\text{Drag}}, \text{ or } \frac{mg}{T} = \frac{L}{D}$$

- Energy = force x distance, so

$$\frac{\text{Total Energy}}{\text{kg}} = \frac{\text{thrust} \times \text{distance}}{\text{mass}} = \frac{Td}{m} = \frac{gd}{L/D}$$

- For an airliner ( $L/D=25$ ) to equal orbital energy,  
 $d=81,000$  km (2 roundtrips NY-Sydney)



# Equivalent Airline Costs?

- Average economy ticket NY-Sydney round-round-trip (Travelocity 9/3/09) ~\$1300
- Average passenger (+ luggage) ~100 kg
- Two round trips = \$26/kg
  - Factor of 60x more than electrical energy costs
  - Factor of 420x less than current launch costs
- But...
  - you get to refuel at each stop!



# Equivalence to Air Transport



- 81,000 km ~ twice around the world
- Voyager - one of two aircraft to ever circle the world non-stop, non-refueled - *once!*



# Orbital Entry - The Physics

- 32 MJ/kg dissipated by friction with atmosphere over  $\sim 8$  min = 66kW/kg
- Pure graphite (carbon) high-temperature material:  
 $c_p = 709 \text{ J/kg}^\circ\text{K}$
- Orbital energy would cause temperature gain of 45,000°K!
- Thus proving the comment about space travel, “It’s utter bilge!” (Sir Richard Wooley, Astronomer Royal of Great Britain, 1956)



# The Vision

“Once you make it to low Earth orbit, you’re halfway to anywhere!”  
- Robert A. Heinlein



# Goals of ENAE 791

- Learn the underlying physics (orbital mechanics, flight mechanics, aerothermodynamics) which constrain and define launch and entry vehicles
- Develop the tools for preliminary design synthesis, including the fundamentals of systems analysis
- Provide an introduction to engineering economics, with a focus on the parameters affecting cost of launch and entry vehicles, such as reusability
- Examine specific challenges in the underlying design disciplines, such as thermal protection and structural dynamics



# Contact Information

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# Web-based Course Content

- Data web site at <http://spacecraft.ssl.umd.edu>
  - Course information
  - Syllabus
  - Lecture notes
  - Problems and solutions
- Interactive web site at <http://elms.umd.edu>
  - Communications for team projects (forums, wiki, blogs)
  - Surveys for course feedback
  - Videos of lectures



# Syllabus Overview (1)

- Fundamentals of Launch and Entry Design
  - Orbital mechanics
  - Basic rocket performance
- Entry flight mechanics
  - Ballistic entry
  - Lifting entry
- Aerothermodynamics
- Thermal Protection System (TPS) analysis
- Entry, Descent, and Landing (EDL) systems



# Syllabus Overview (2)

- Launch flight mechanics
  - Gravity turn
  - Targeted trajectories
  - Optimal trajectories
  - Airbreathing trajectories
- Launch vehicle systems
  - Propulsion systems
  - Structures and structural dynamics analysis
  - Avionics
  - Payload accommodations
  - Ground launch processing



# Syllabus Overview (3)

- Systems Analysis
  - Cost estimation
  - Engineering economics
  - Reliability issues
  - Safety design concerns
  - Fleet resiliency
  - Multidisciplinary optimization
- Case studies
- Design project



# Policies

- Grade Distribution
  - 25% Problems
  - 20% Midterm Exam
  - 25% Term Project
  - 30% Final Exam
- Late Policy
  - On time: Full credit
  - Before solutions: 70% credit
  - After solutions: 20% credit



# A Word on Homework Submissions...

- Good methods of handing in homework
  - Hard copy in class (best!)
  - Scanned copies via e-mail  
(please put “ENAE791” in the subject line)
- Methods that don't work so well
  - Leaving it in my mailbox (particularly in EGR)
  - Leaving it in my office
  - Spreadsheets or .m files
  - Handing it to me in random locations
  - Handing it to Dr. Bowden

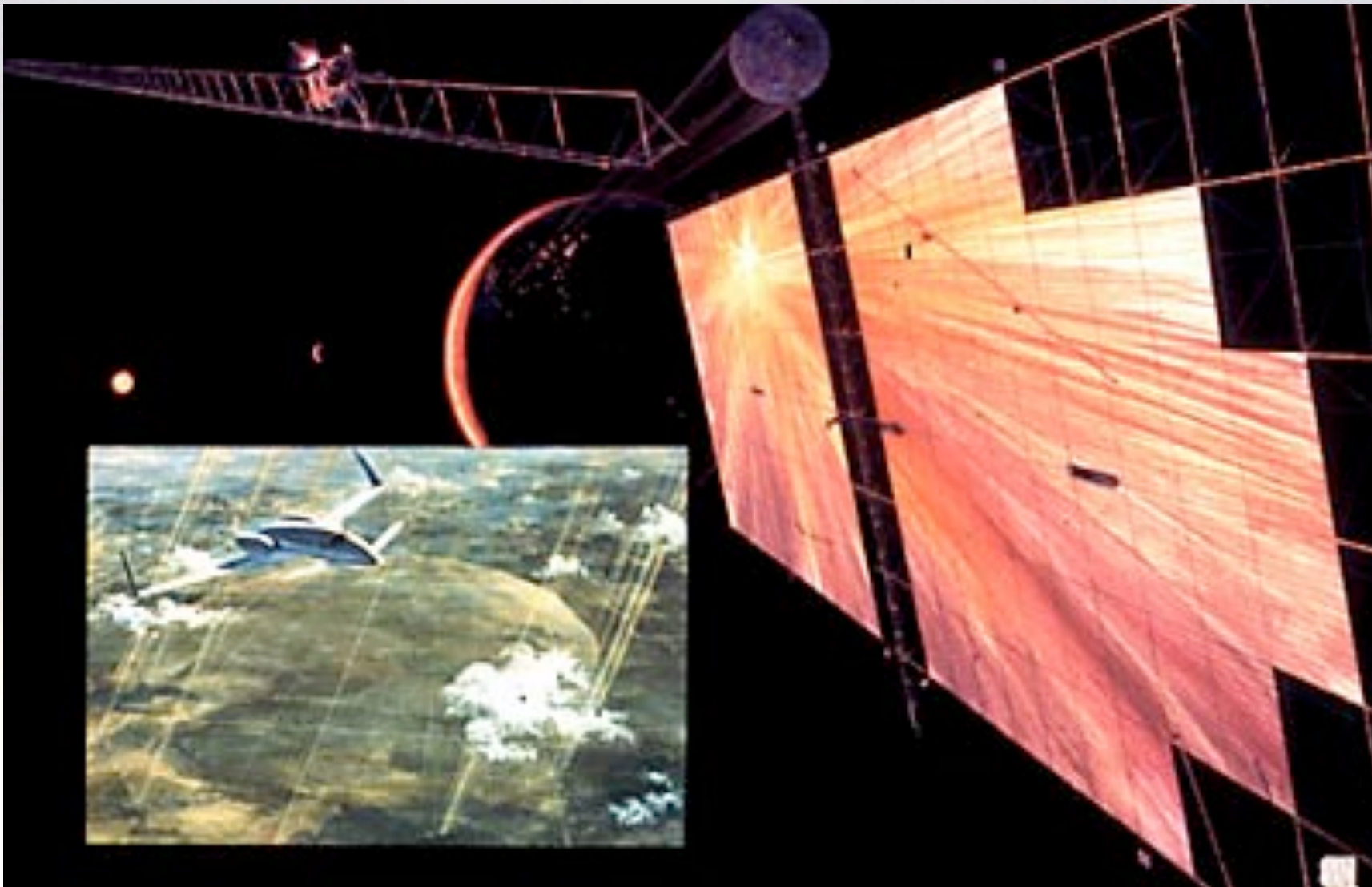


# A Word about Homework Grading

- Homework is graded via a discrete filter
  - ✓ for homework problems which are essentially correct (10 pts)
  - ✓- for homework with significant problems (7 pts)
  - ✓-- for homework with major problems (4 pts)
  - ✓+ for homework demonstrating extra effort (12 pts)
  - 0 for missing homework
- A detailed solution document is posted for each problem after the due date, which you should review to ensure you understand the techniques used



# Term Project - Solar Power Satellites



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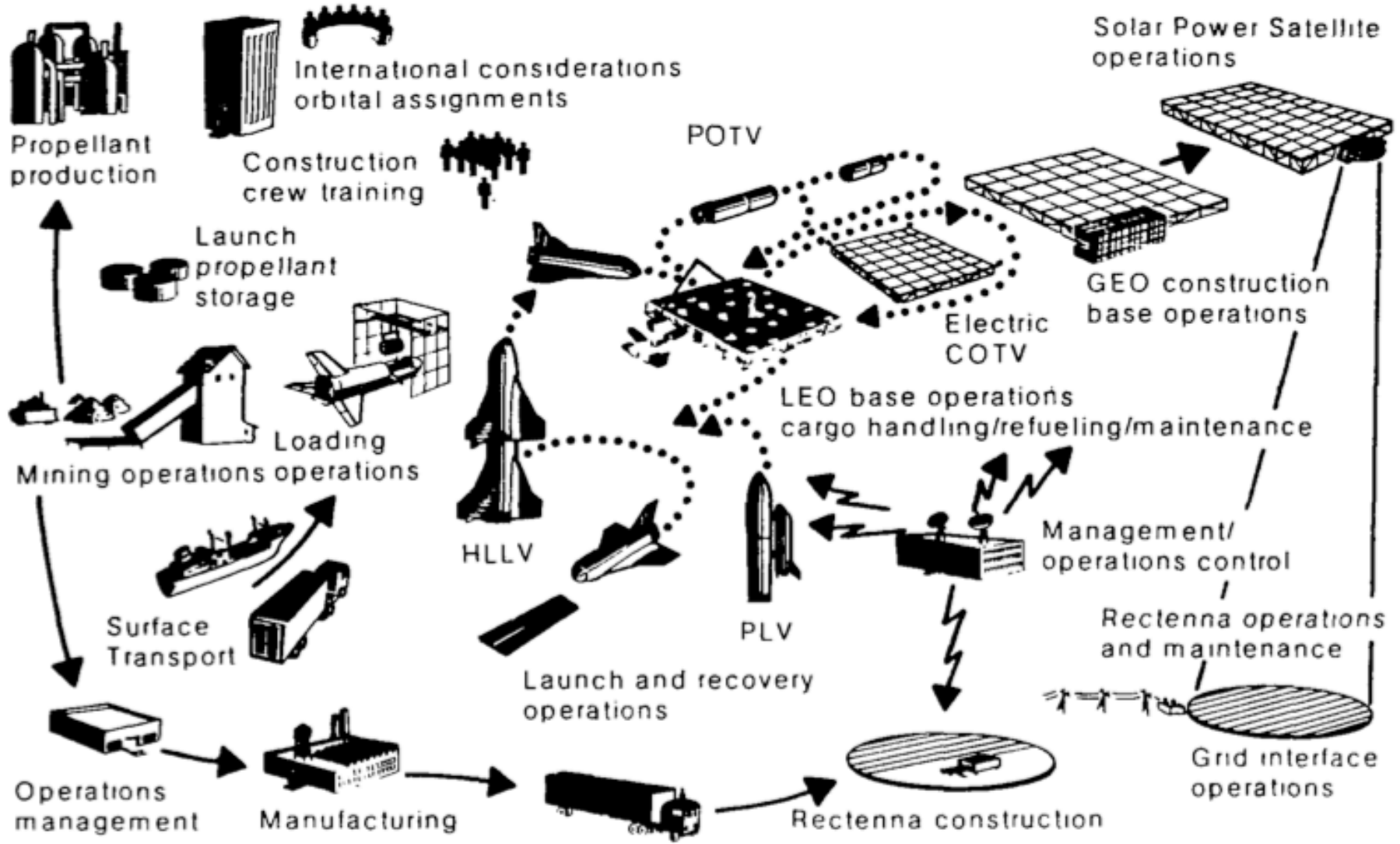
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# Term Project - Top Level Requirements

- Design a system to allow the construction of one 10GW SPS per year
  - Launch vehicle(s) for cargo and personnel
  - Crew-carrying spacecraft
  - On-orbit transportation infrastructure
  - Assembly base(s) siting analysis
  - Spacecraft launch abort and EDL systems
- Mission models
  - 4000 MT/year for SPS components
  - All other logistics over and above SPS payloads



# SPS Operational Scenario (NASA - 1981)



# Term Project

- Form your own teams (~3-4/team)
- Design an architecture to support SPS construction and operations in the most cost effective manner possible
- All vehicles will be conceptually designed from scratch (no “catalog engineering”!)
- Parametric design parameters will be provided for human spacecraft systems not ENAE791-relevant
- Design process should proceed throughout the term
- Formal design presentations at end of term



# Orbital Mechanics: 500 years in 40 min.

- Newton's Law of Universal Gravitation

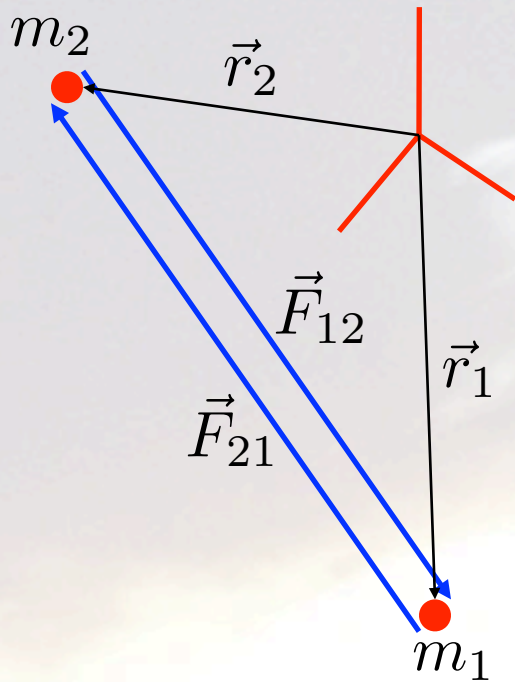
$$F = \frac{Gm_1m_2}{r^2}$$

- Newton's First Law meets vector algebra

$$\vec{F} = m\vec{a}$$



# Relative Motion Between Two Bodies



$$m_1 \frac{d^2 \vec{r}_1}{dt^2} = G \frac{m_1 m_2}{|\vec{r}_{21}|^2} \frac{\vec{r}_{21}}{|\vec{r}_{21}|}$$

$$= G \frac{m_1 m_2}{|\vec{r}_{21}|^3} \vec{r}_{21} = G \frac{m_1 m_2}{|\vec{r}_{21}|^3} (\vec{r}_2 - \vec{r}_1)$$

$$m_2 \frac{d^2 \vec{r}_2}{dt^2} = G \frac{m_1 m_2}{|\vec{r}_{12}|^3} (\vec{r}_1 - \vec{r}_2)$$

$\vec{F}_{12}$  = force due to body 1 on body 2



# Gravitational Motion

$$\frac{d^2 \vec{r}}{dt^2} = \frac{G}{r^3} [m_2 (-\vec{r}) - m_1 (\vec{r})] = \frac{-G}{r^3} (m_1 + m_2) \vec{r}$$

$$\text{Let } r = |\vec{r}_{12}| = |\vec{r}_{21}| \quad \text{Let } \vec{r} = \vec{r}_1 - \vec{r}_2$$

$$\text{Let } \mu = G(m_1 + m_2)$$

$$\frac{d^2 \vec{r}}{dt^2} + \mu \frac{\vec{r}}{r^3} = \vec{0}$$

“Equation of Orbit” -

Orbital motion is simple harmonic motion



# Orbital Angular Momentum

$$\vec{v} = \frac{d\vec{r}}{dt} \quad \frac{d\vec{v}}{dt} + \mu \frac{\vec{r}}{r^3} = \vec{0}$$

$$\vec{r} \times \frac{d\vec{v}}{dt} + \frac{\mu}{r^3} (\vec{r} \times \vec{r}) = \vec{0}$$

$$\vec{r} \times \frac{d\vec{v}}{dt} = \vec{0}$$

$$\frac{d}{dt} (\vec{r} \times \vec{v}) = \frac{d\vec{r}}{dt} \times \vec{v} + \vec{r} \times \frac{d\vec{v}}{dt}$$

$$= \vec{v} \times \vec{v} + \vec{r} \times \frac{d\vec{v}}{dt} = \vec{r} \times \frac{d\vec{v}}{dt} = \vec{0}$$

$$\frac{d}{dt} (\vec{r} \times \vec{v}) = \vec{0}$$

$$\vec{r} \times \vec{v} = \text{constant}$$

$$\vec{r} \times \vec{v} = \vec{h}$$

$\vec{h}$  is angular momentum vector (constant)  $\implies$   
 $\vec{r}$  and  $\vec{v}$  are in a constant plane



# Fun and Games with Algebra

$$\frac{d\vec{v}}{dt} + \mu \frac{\vec{r}}{r^3} = \vec{0}$$

$$\frac{d\vec{v}}{dt} \times \vec{h} + \frac{\mu}{r^3} (\vec{r} \times \vec{h}) = \vec{0}$$

$$\frac{d}{dt} (\vec{v} \times \vec{h}) = \frac{d\vec{v}}{dt} \times \vec{h} + \vec{v} \times \frac{d\vec{h}}{dt}$$

$$\frac{d}{dt} (\vec{v} \times \vec{h}) = -\frac{\mu}{r^3} (\vec{r} \times \vec{h}) = -\frac{\mu}{r^3} (\vec{r} \times \vec{r} \times \vec{v})$$

$$\frac{d}{dt} (\vec{v} \times \vec{h}) = -\frac{\mu}{r^3} [(\vec{r} \cdot \vec{v}) \vec{r} - (\vec{r} \cdot \vec{r}) \vec{v}]$$

$$\vec{r} \cdot \vec{v} = r v \cos \gamma = r \frac{dr}{dt}$$



# More Algebra, More Fun

$$\frac{d}{dt} \left( \vec{v} \times \vec{h} \right) = -\frac{\mu}{r^3} \left[ r \frac{dr}{dt} \vec{r} - r^2 \frac{d\vec{r}}{dt} \right]$$

$$\frac{d}{dt} \left( \frac{\vec{r}}{r} \right) = \frac{\left( r \frac{d\vec{r}}{dt} - \vec{r} \frac{dr}{dt} \right)}{r^2} = \left( \frac{1}{r} \frac{d\vec{r}}{dt} - \frac{\vec{r}}{r^2} \frac{dr}{dt} \right)$$

$$\frac{d}{dt} \left( \vec{v} \times \vec{h} \right) = -\mu \left( \frac{1}{r^2} \frac{dr}{dt} \vec{r} - \frac{1}{r} \frac{d\vec{r}}{dt} \right) = \mu \frac{d}{dt} \left( \frac{\vec{r}}{r} \right)$$

$$\frac{d}{dt} \left( \vec{v} \times \vec{h} - \mu \frac{\vec{r}}{r} \right) = \vec{0}$$



# Orientation of the Orbit

$$\vec{v} \times \vec{h} - \mu \frac{\vec{r}}{r} = \text{constant}$$

$$\vec{v} \times \vec{h} - \mu \frac{\vec{r}}{r} = \mu \vec{e}$$

$\vec{e} \equiv$  eccentricity vector, in orbital plane

$\vec{e}$  points in the direction of periapsis

$$\vec{r} \cdot \vec{v} \times \vec{h} - \vec{r} \cdot \mu \frac{\vec{r}}{r} = \mu (\vec{r} \cdot \vec{e})$$

$$\vec{r} \times \vec{v} \cdot \vec{h} - \mu \frac{\vec{r} \cdot \vec{r}}{r} = \mu r e \cos \theta$$

$$\vec{h} \cdot \vec{h} - \mu \frac{r^2}{r} = \mu r e \cos \theta$$



# Position in Orbit

$$h^2 - \mu r = \mu r e \cos \theta$$

$$r = \frac{h^2 / \mu}{1 + e \cos \theta}$$

$\theta$  = true anomaly: angular travel from perigee passage

$$\text{at } \theta = \pm \frac{\pi}{2}; \cos \theta = 0; r = p \equiv h^2 / \mu$$



# Relating Velocity and Orbital Elements

$$\mu \vec{e} = \vec{v} \times \vec{h} - \mu \frac{\vec{r}}{r}$$

$$\mu \vec{e} \cdot \mu \vec{e} = \vec{v} \times \vec{h} \cdot \vec{v} \times \vec{h} - 2\mu \left( \vec{v} \times \vec{h} \right) \cdot \frac{\vec{r}}{r} + \mu^2 \left( \frac{\vec{r}}{r} \cdot \frac{\vec{r}}{r} \right)$$

$$\mu^2 e^2 = v^2 h^2 - 2\mu \frac{h^2}{r} + \mu^2$$

$$e^2 = \frac{v^2}{\mu} p - 2 \frac{p}{r} + 1$$



# Vis-Viva Equation

$$p \equiv a(1 - e^2) = \frac{1 - e^2}{\frac{2}{r} - \frac{v^2}{\mu}}$$

$$a = \left( \frac{2}{r} - \frac{v^2}{\mu} \right)^{-1}$$

$$v^2 = \mu \left( \frac{2}{r} - \frac{1}{a} \right)$$

$$\frac{v^2}{2} - \frac{\mu}{r} = -\frac{\mu}{2a}$$



# Energy in Orbit

- Kinetic Energy

$$K.E. = \frac{1}{2} m v^2 \Rightarrow \frac{K.E.}{m} = \frac{v^2}{2}$$

- Potential Energy

$$P.E. = -\frac{m\mu}{r} \Rightarrow \frac{P.E.}{m} = -\frac{\mu}{r}$$

- Total Energy

$$Const. = \frac{v^2}{2} - \frac{\mu}{r} = -\frac{\mu}{2a}$$

<--Vis-Viva Equation



# Suborbital Tourism - Spaceship Two



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Tuesday, January 31, 2012

# How Close are we to Space Tourism?

- Energy for 100 km vertical climb

$$-\frac{\mu}{r_E + 100 \text{ km}} + \frac{\mu}{r_E} = 0.965 \frac{\text{km}^2}{\text{sec}^2} = 0.965 \frac{\text{MJ}}{\text{kg}}$$

- Energy for 200 km circular orbit

$$-\frac{\mu}{2(r_E + 200 \text{ km})} + \frac{\mu}{r_E} = 32.2 \frac{\text{km}^2}{\text{sec}^2} = 32.2 \frac{\text{MJ}}{\text{kg}}$$

- Energy difference is a factor of 33!



# Implications of Vis-Viva

- Circular orbit ( $r=a$ )

$$v_{circular} = \sqrt{\frac{\mu}{r}}$$

- Parabolic escape orbit ( $a$  tends to infinity)

$$v_{escape} = \sqrt{\frac{2\mu}{r}}$$

- Relationship between circular and parabolic orbits

$$v_{escape} = \sqrt{2}v_{circular}$$



# Some Useful Constants

- Gravitation constant  $\mu = GM$ 
  - Earth:  $398,604 \text{ km}^3/\text{sec}^2$
  - Moon:  $4667.9 \text{ km}^3/\text{sec}^2$
  - Mars:  $42,970 \text{ km}^3/\text{sec}^2$
  - Sun:  $1.327 \times 10^{11} \text{ km}^3/\text{sec}^2$
- Planetary radii
  - $r_{\text{Earth}} = 6378 \text{ km}$
  - $r_{\text{Moon}} = 1738 \text{ km}$
  - $r_{\text{Mars}} = 3393 \text{ km}$



# Classical Parameters of Elliptical Orbits

