## **Space Simulation**

- Focus of this lecture is on human-in-the-loop operational simulations, not component sims (e.g., thermal vacuum chambers)
- Microgravity
- Planetary surfaces
- Specialty simulations



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## **Microgravity Simulation Approaches**

- Parabolic flight
- Neutral buoyancy
- Suspension harnesses
- Flat floors





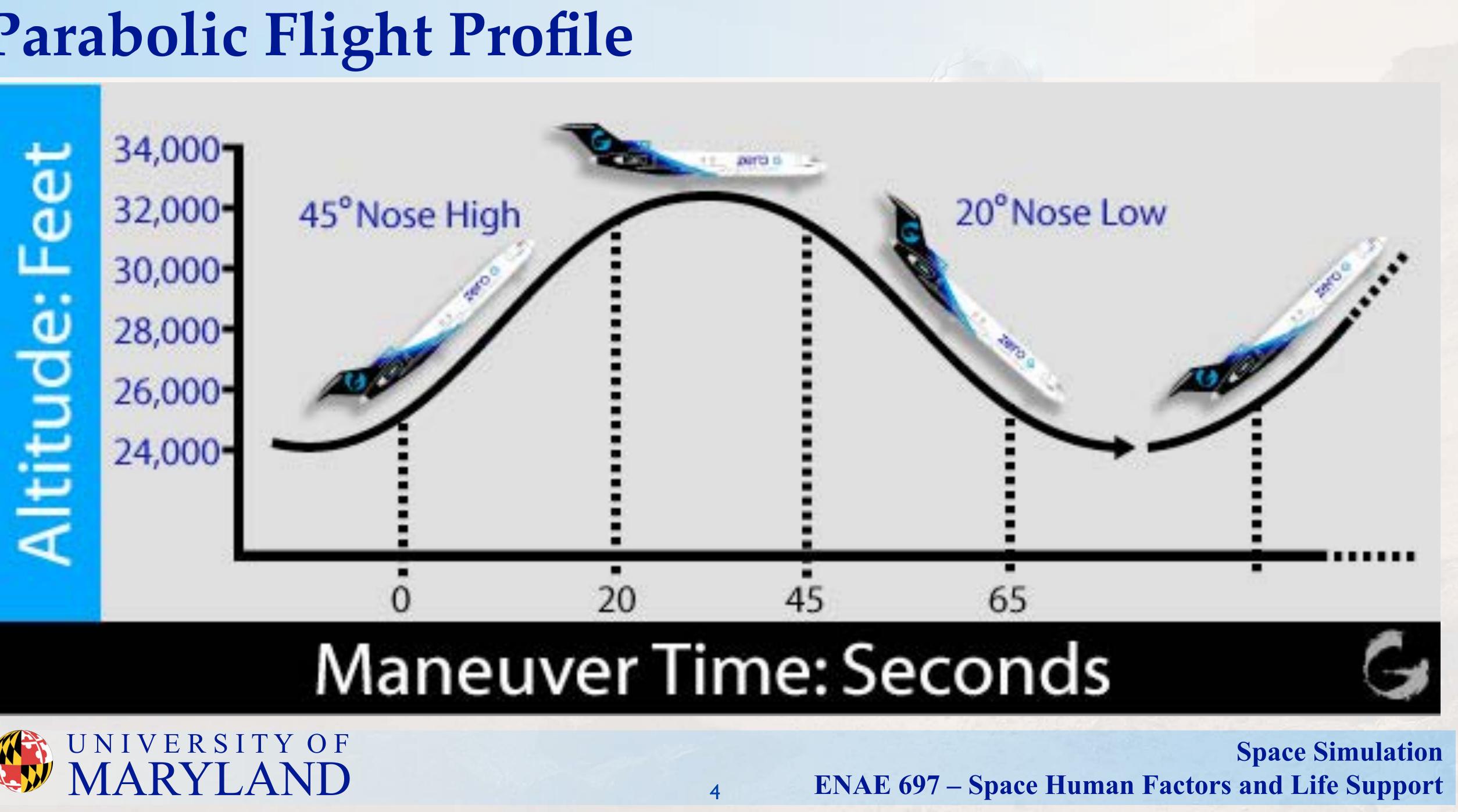
## NASA KC-135 in Parabolic Flight







## Parabolic Flight Profile





## Parabolic Flight Summary

- Advantages
  - Actual microgravity
- Disadvantages
  - Motion sickness
  - Limits of cabin volume
  - Limited time
  - Limited crew size
  - Substantial certification requirements
  - High cost (~\$5-10K/flight hour)

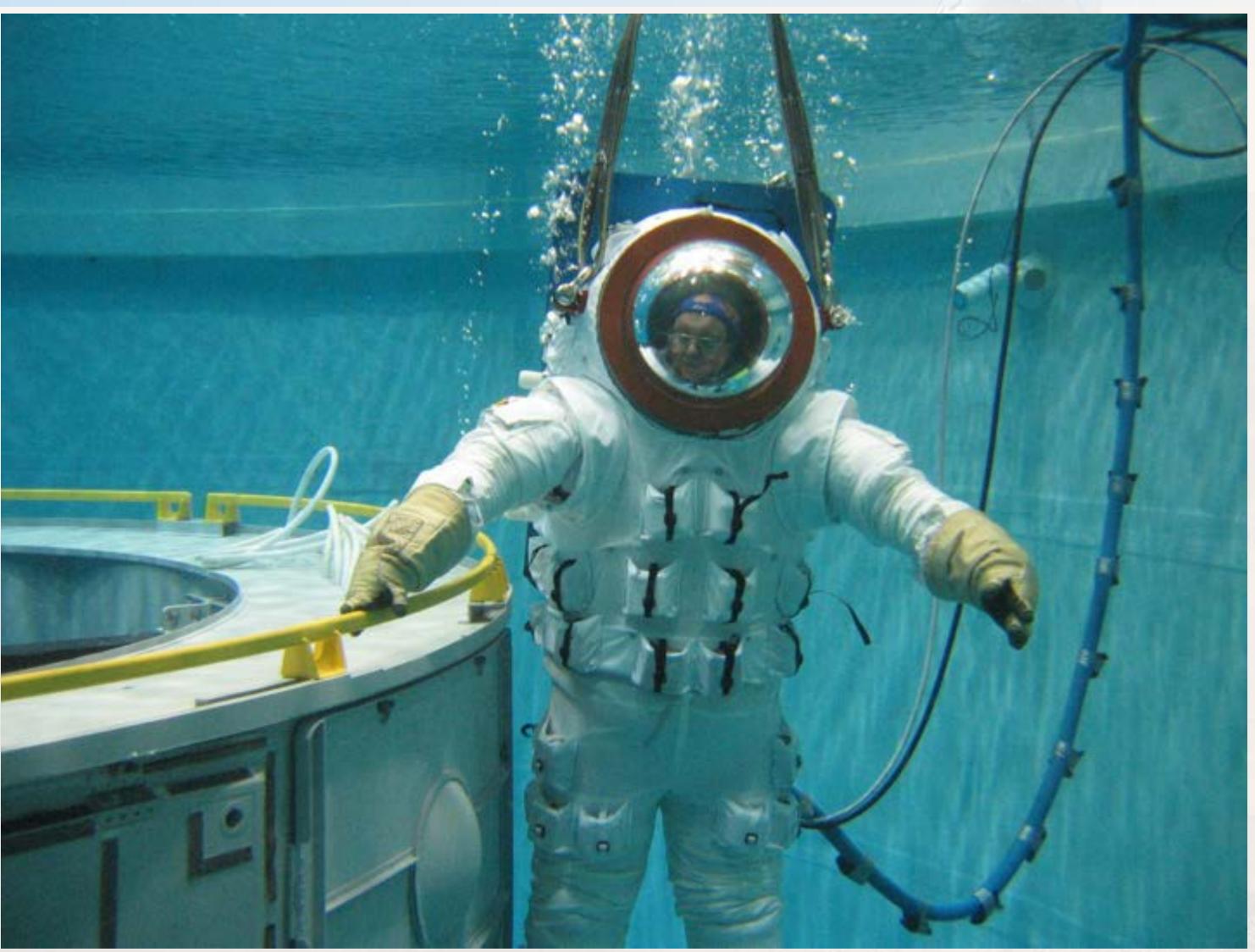
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## Neutral Buoyancy Simulation of µG



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## **Potential Applications of UW Simulation**

- EVA Interfaces
  - Installation of science packages
  - Rover ingress / egress / seating
  - Habitat access (e.g., ladders, stairs, ramps)
  - Pressure suit design evaluation (e.g., foot visibility, recovery from fall)
- Ergonomics and human factors
  - Partial gravity neutral body posture and postural maintenance
  - Effects of backpack weight and CG on balance
  - Reach envelopes with strength correlation
- Walking and other gaits
  - Use of treadmill to reduce effects of water drag (primarily leg motion)
  - backpack size and mass on gaits and stability



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– Useful for evaluating pressure suit design for mobility, understanding effect of



## Neutral Buoyancy Summary

- Advantages
  - No restrictions on number or relative position of items
  - No significant time limitations
  - Few size limitations to workspace
- Disadvantages

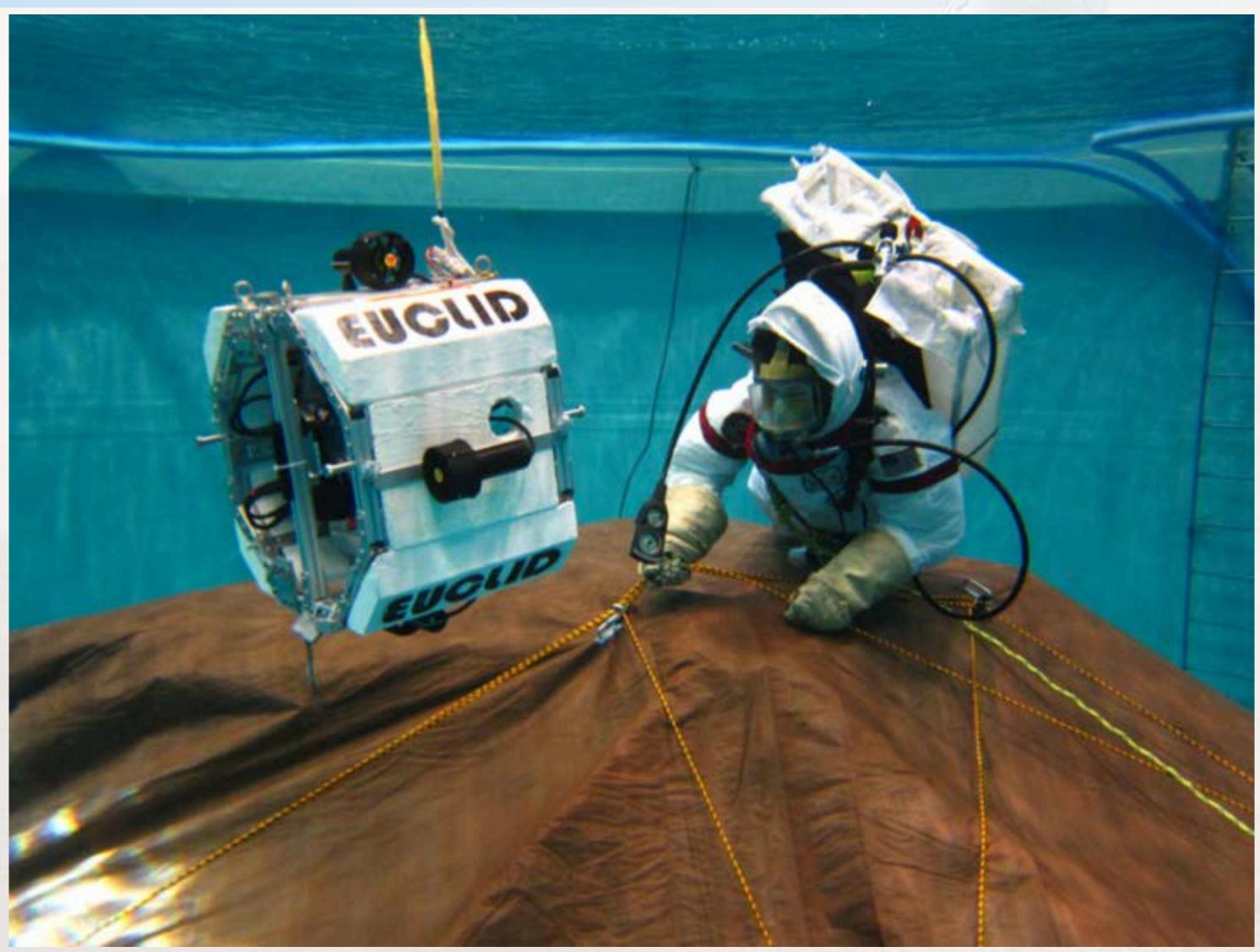
  - Hydrodynamic effects (especially damping) Need to waterproof hardware (particularly sensors) All items must have net specific gravity=1 Significant subject qualification requirements - Limited access to test environment (except us!)

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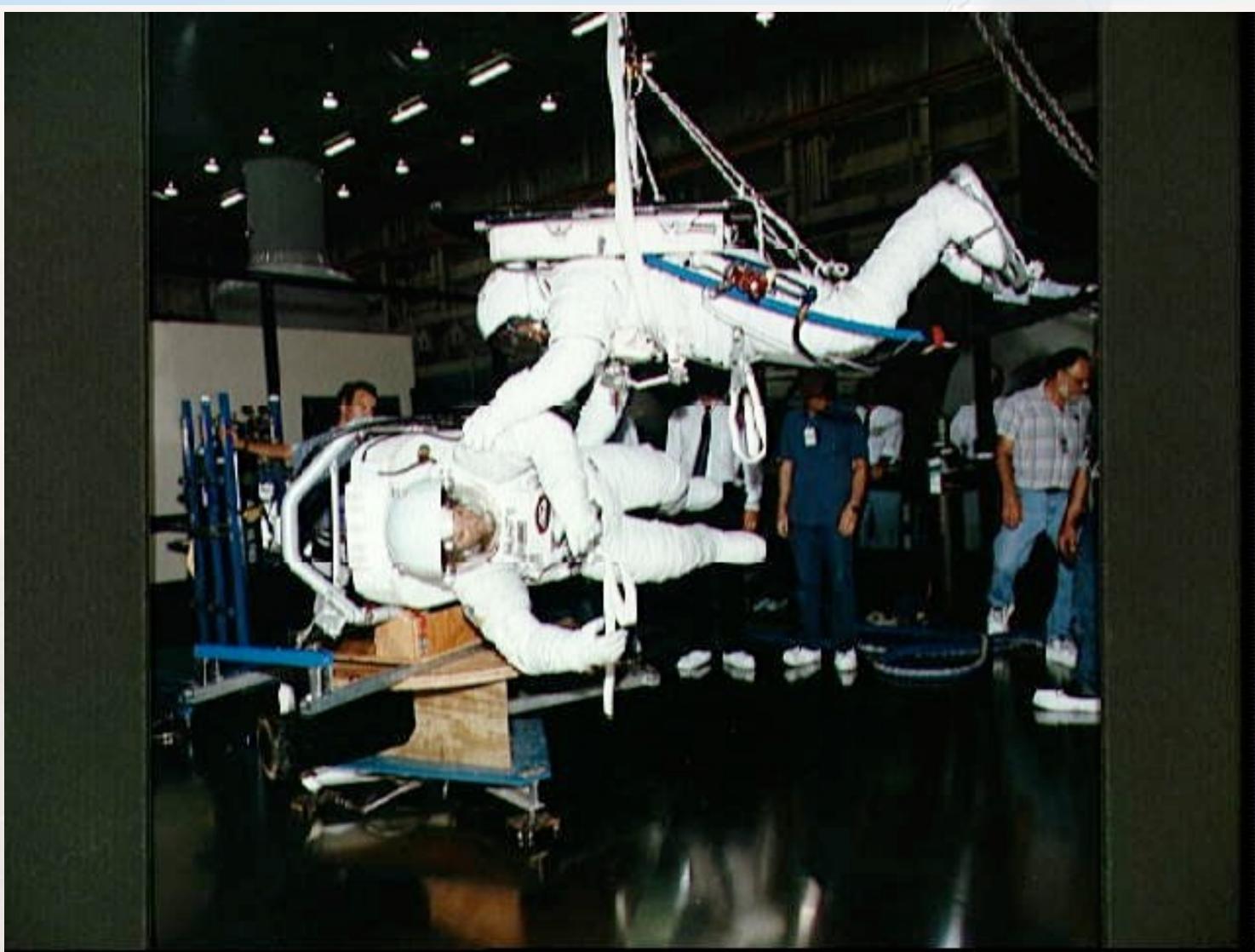
## **MX-B Suit Simulator in Asteroid Tests**







## **Air-Bearing Floor/Suspension Harness**







## **Air-Bearing Floor Summary**

- Advantages
  - Somewhat realistic 2D dynamics
- Disadvantages
  - Dedicated facility requirements
  - Acoustic issues
  - Boundary control
  - Limited configurations (no over/under transits)





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## **Suspension Harness Summary**

- Advantages
  - Cheap
- Disadvantages
  - Limited dynamic fidelity
  - Pendulum modes (need high ceilings)
  - Comfort/safety



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## Simulation of Partial Gravity Ops • Only major activity dates back to Apollo Science and operational issues to be examined

- - Biomechanics
  - Mobility
  - Sampling
  - Instrument placement
  - Equipment development
  - Pressure suit design
  - Field exploration

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## **Approaches to Partial Gravity Sims**

- Parabolic flight
- Counterbalance suspension
- Inclined suspension
- 1g simulations
- Ballasted underwater testing



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## Parabolic Flight

- True "partial gravity" during parabolic pushover
- Same disadvantages as in microgravity section
- Primarily used for interface testing

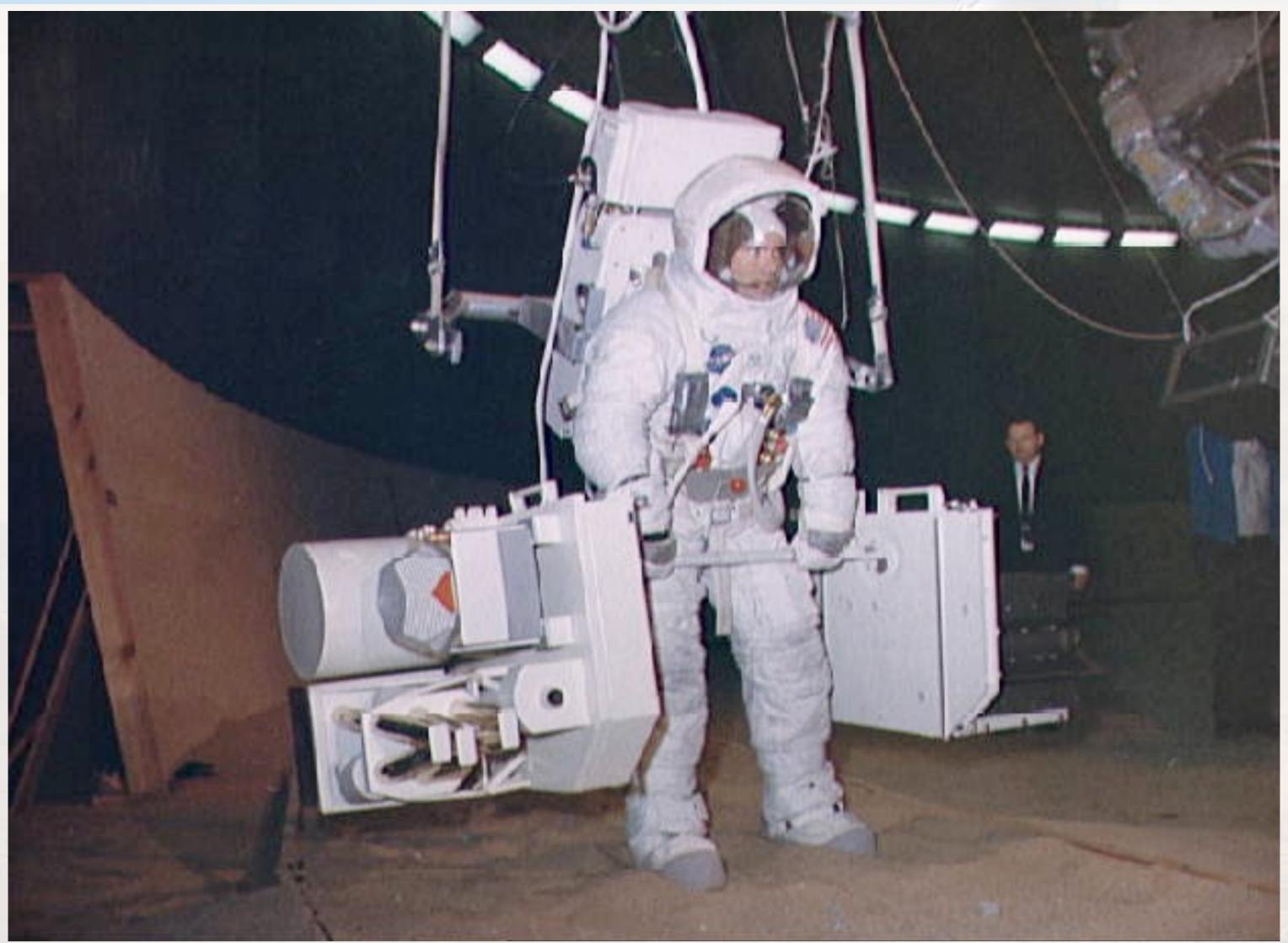




## g parabolic pushover icrogravity section



## **Counterweighted Suspension**





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## **Counterweighted Suspension**

- Numerous approaches to offsetting portion of Earth weight
  - Mass counterbalance
  - Linear springs
  - Nonlinear (e.g., constant-force) springs
  - Active force control
  - Buoyant offset (e.g., balloons)
- Generally limited to counterbalance of gross body weight - Gimbaled harness required for body rotational freedom

  - Difficult to counterbalance individual limbs
- subject, provide counterbalance for test hardware

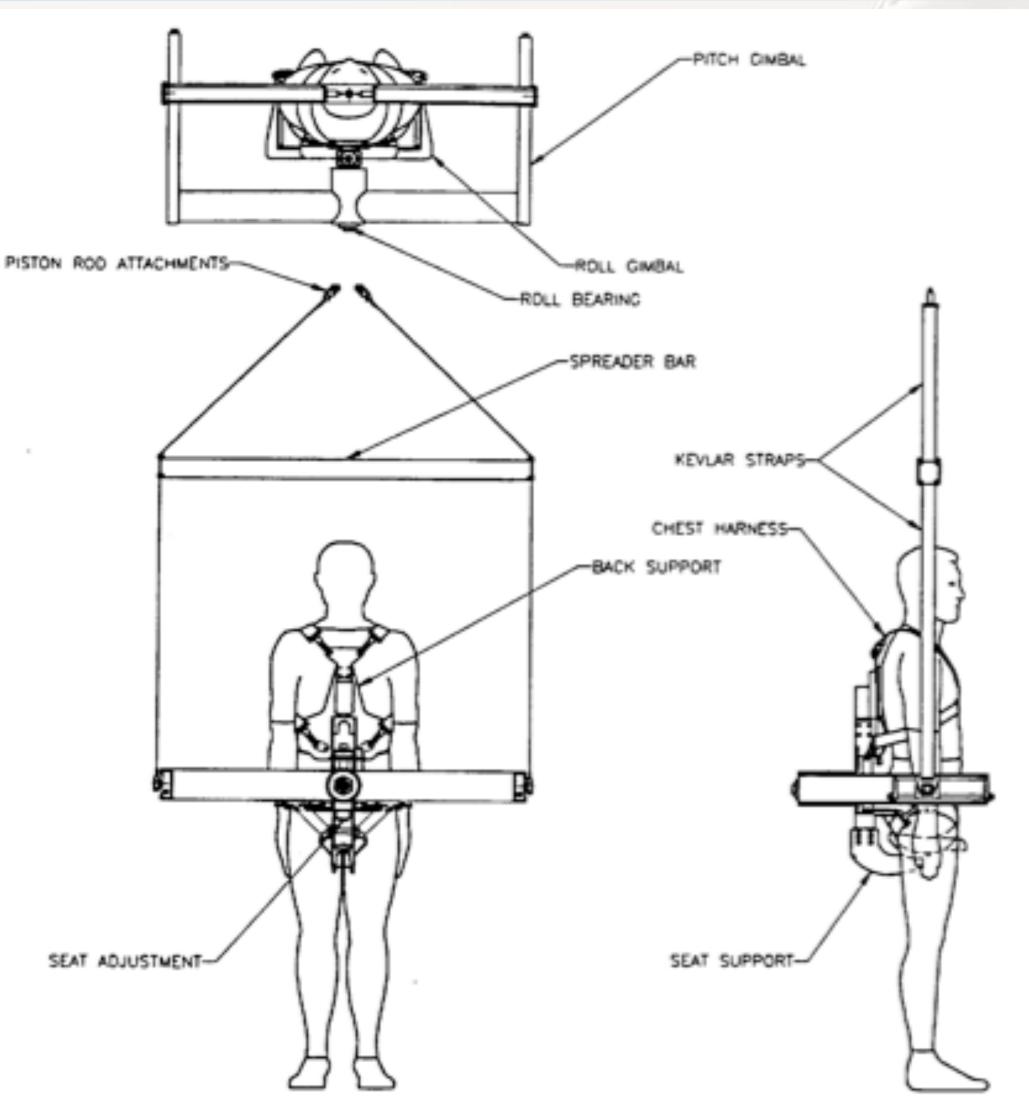
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 Additional complexity required to maintain suspension point above test • Best suited to interior simulations with limited traverses

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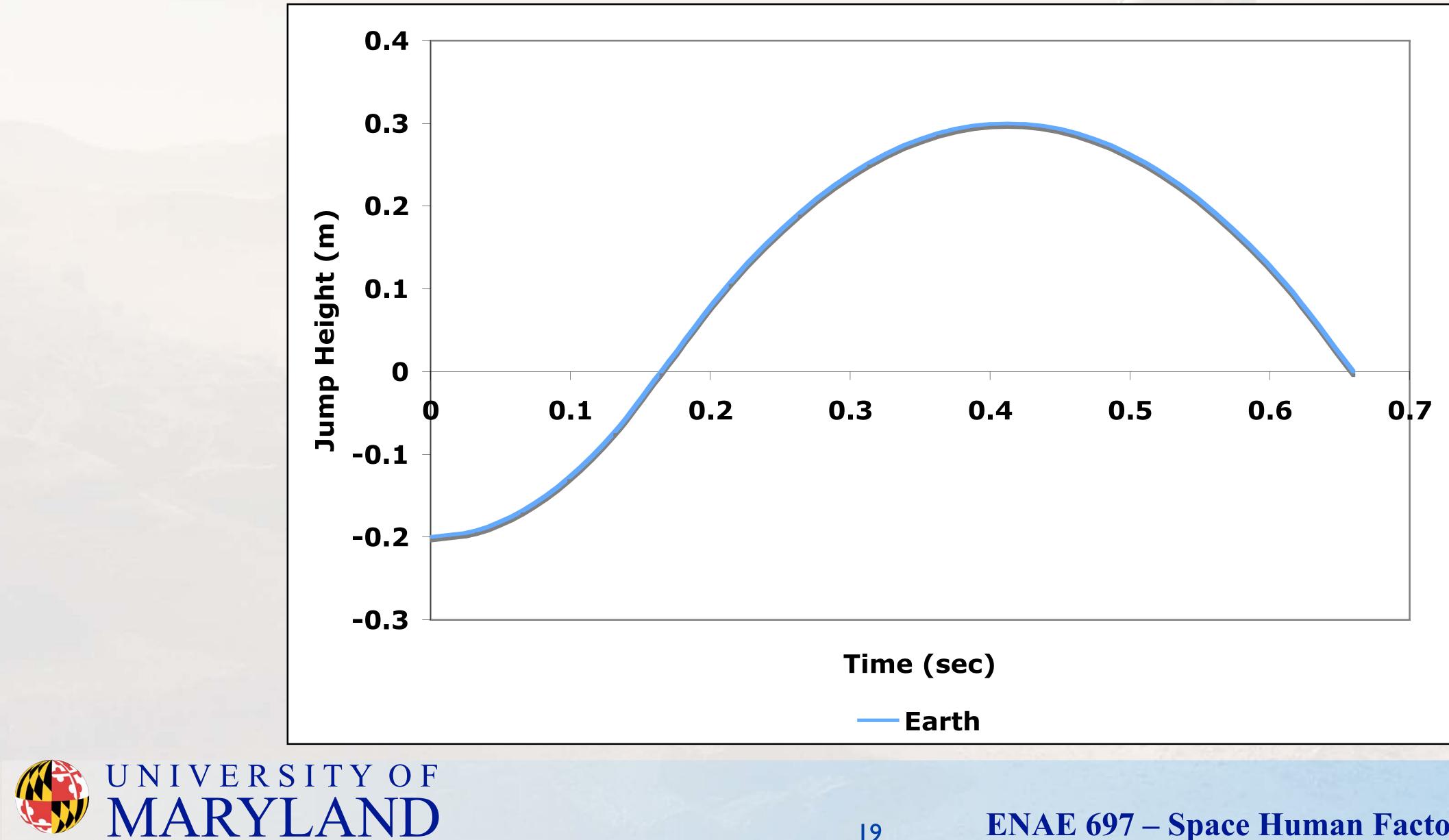
## Active Suspension Body Gimbals







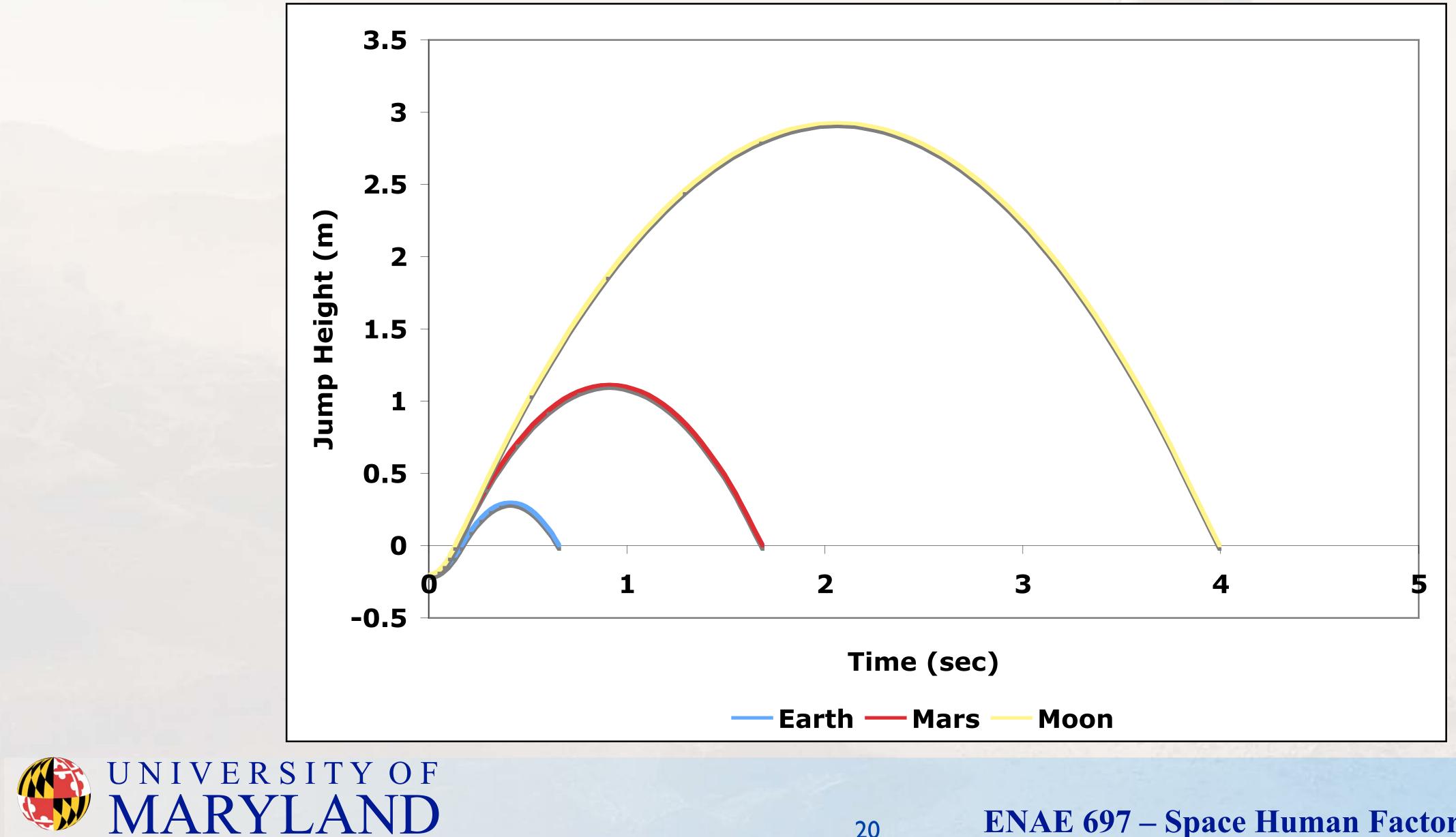
## Vertical Jump Profile (Earth)



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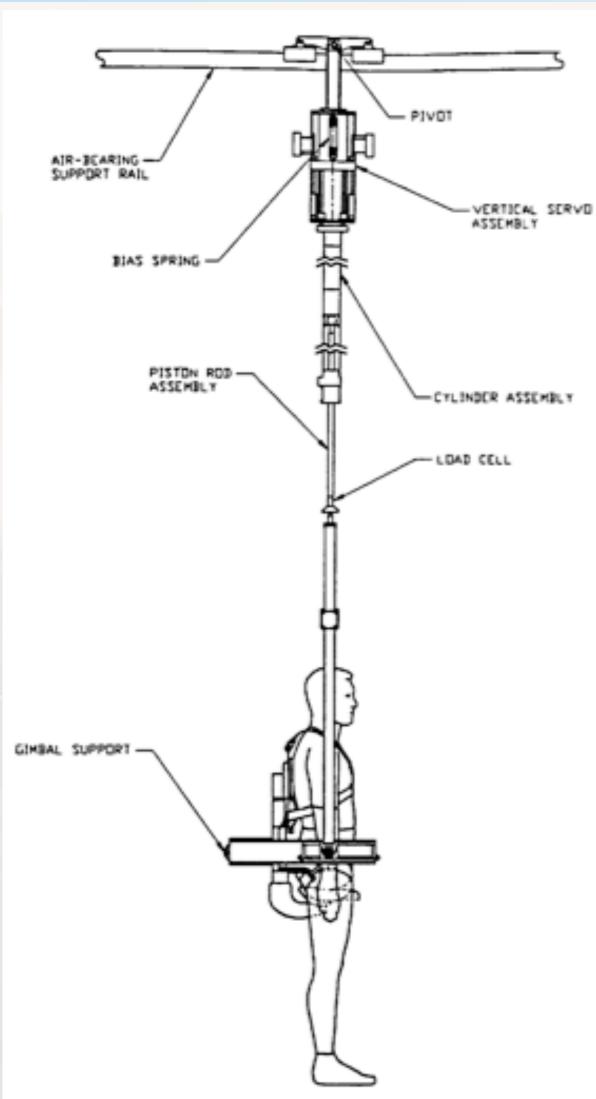
## **Comparative Vertical Jump Profiles**



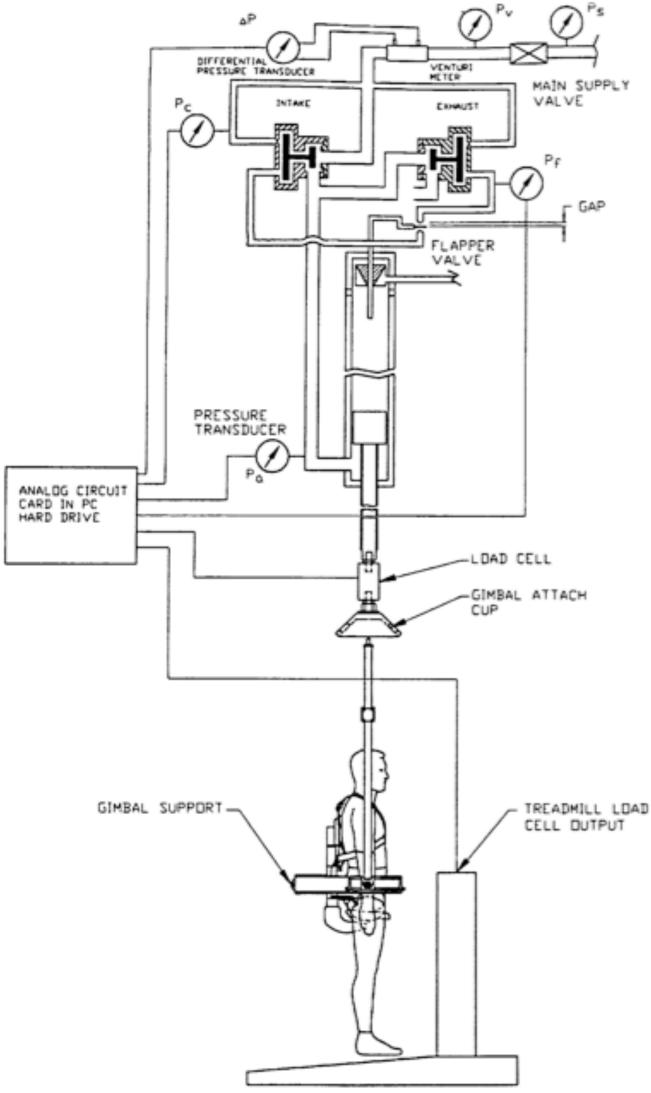
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## **Active Suspension Approaches**







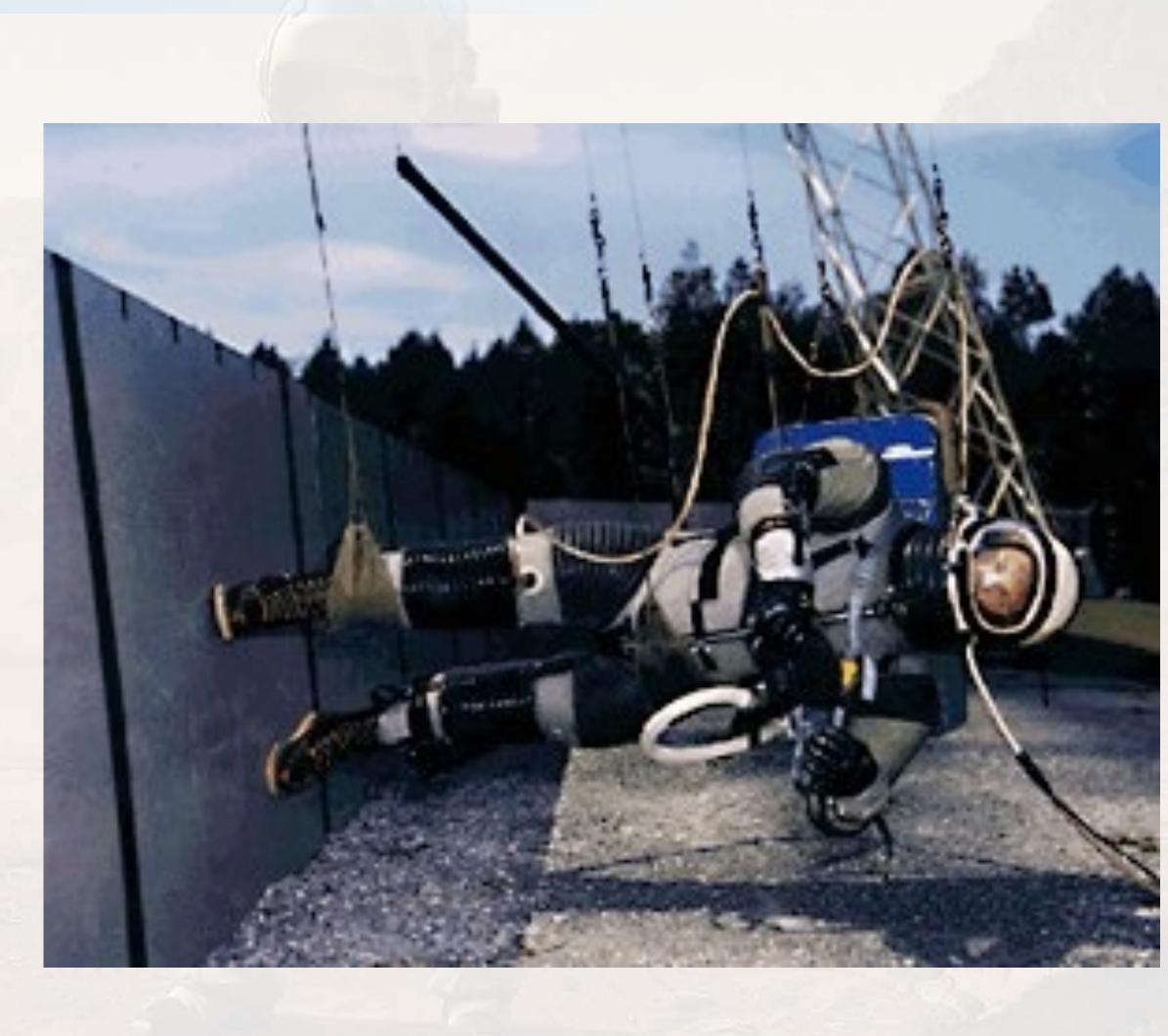
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## Inclined Suspension

- Provides appropriate normal force to inclined wall
  - Lunar simulation angle 80.8°
  - Mars simulation angle 67.7°
- Requires complex suspension system
  - Complex rigid harness required to suspend lower leg without interference to upper leg
  - Pendulum dynamics based on length of wires
  - Overhead suspension point must follow subject motion
- Best suited to mobility studies





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## NASA LaRC Video of Inclined Sims

## Exploratory Study of Man's Self-Locomotion Capabilities With a Space Suit in Lunar Gravity. By Amos A. Spady, Jr., and William D. Krasnow.





## **1 g Testing**

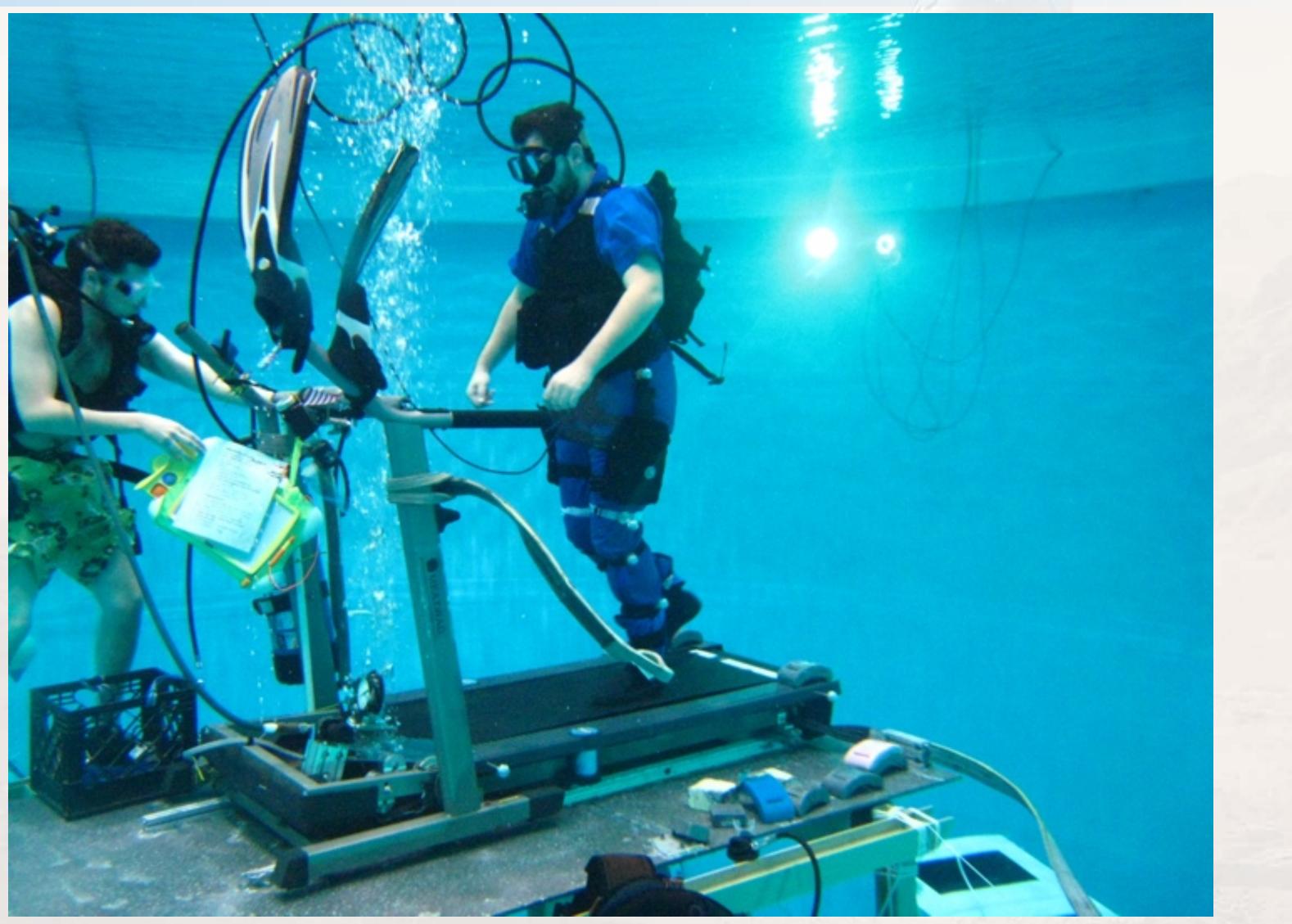
- Approach: ignore entire issue of partial gravity; test in Earth-normal conditions
- Enabled by non-flight configuration for selected systems
  - External life support
  - Lightweight backpacks, instrument mockups
  - Use of additional personnel for relieving crew from some tasks
  - Omission of pressure suit for some field testing
- Primarily used for crew training





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## **Partial Gravity Simulation Underwater**



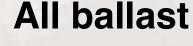




## **Ballasting for UW Planetary Simulation**

**IVA Simulation assuming 150 lb test subject** 

Body Segment	Lunar Ballast	Mars Ballast
Torso/Head	12.1	28.5
Upper Arm (each)	0.7	1.5
Lower Arm (each)	0.5	1.3
Thigh (each)	3.4	8.1
Lower Leg (each)	1.4	3.2
Totals	24	57



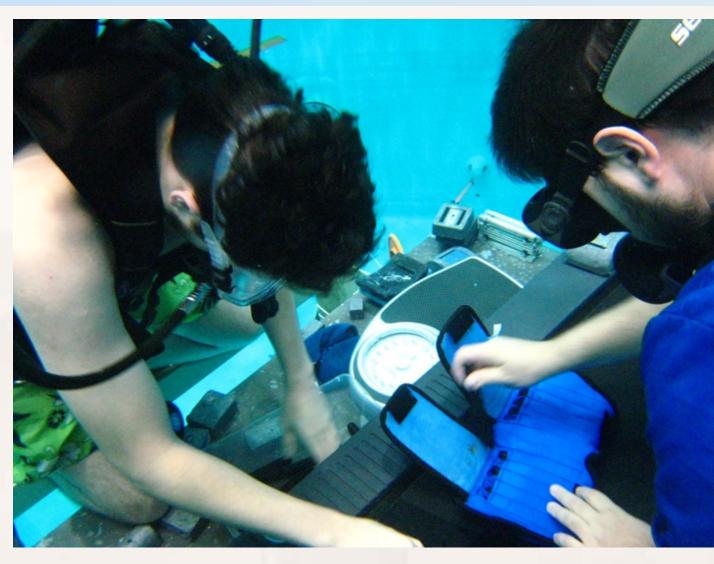


All ballast weights in pounds

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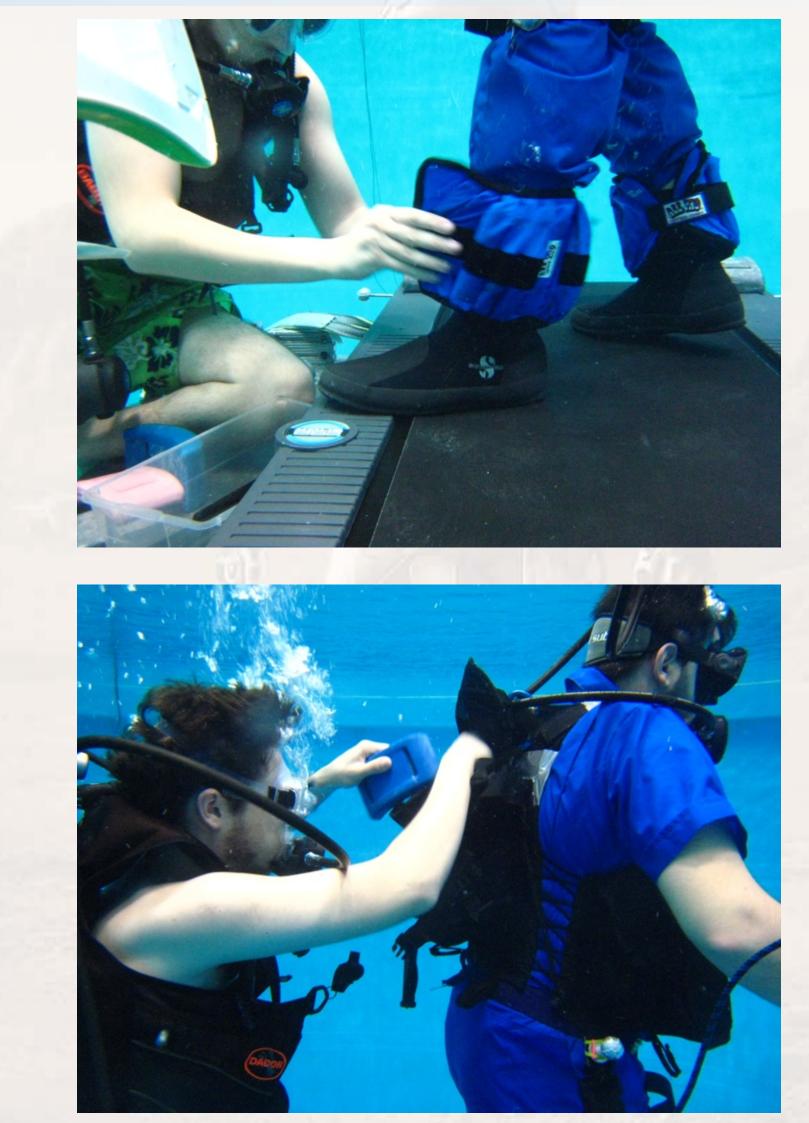


## **Ballasting the Test Subject**



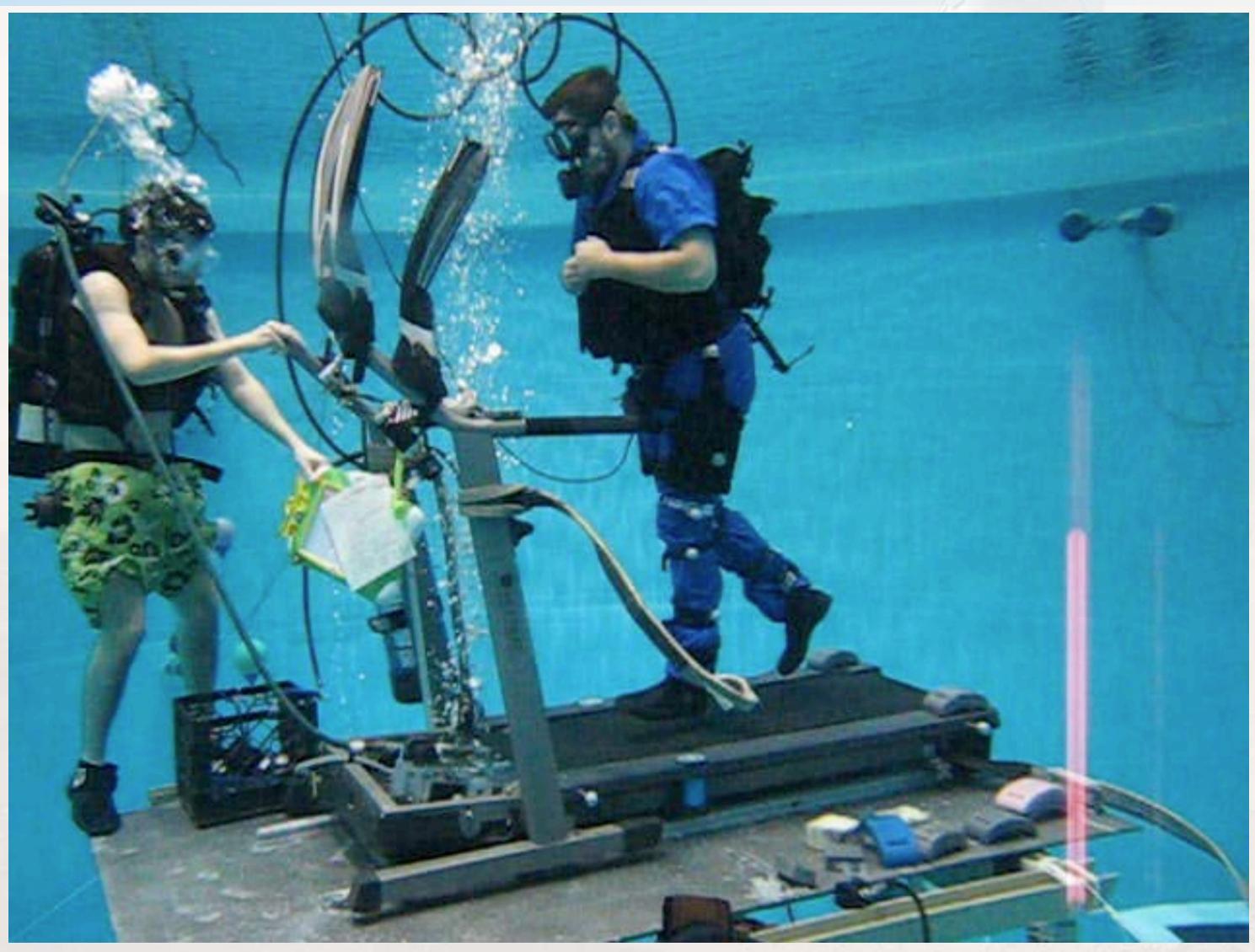








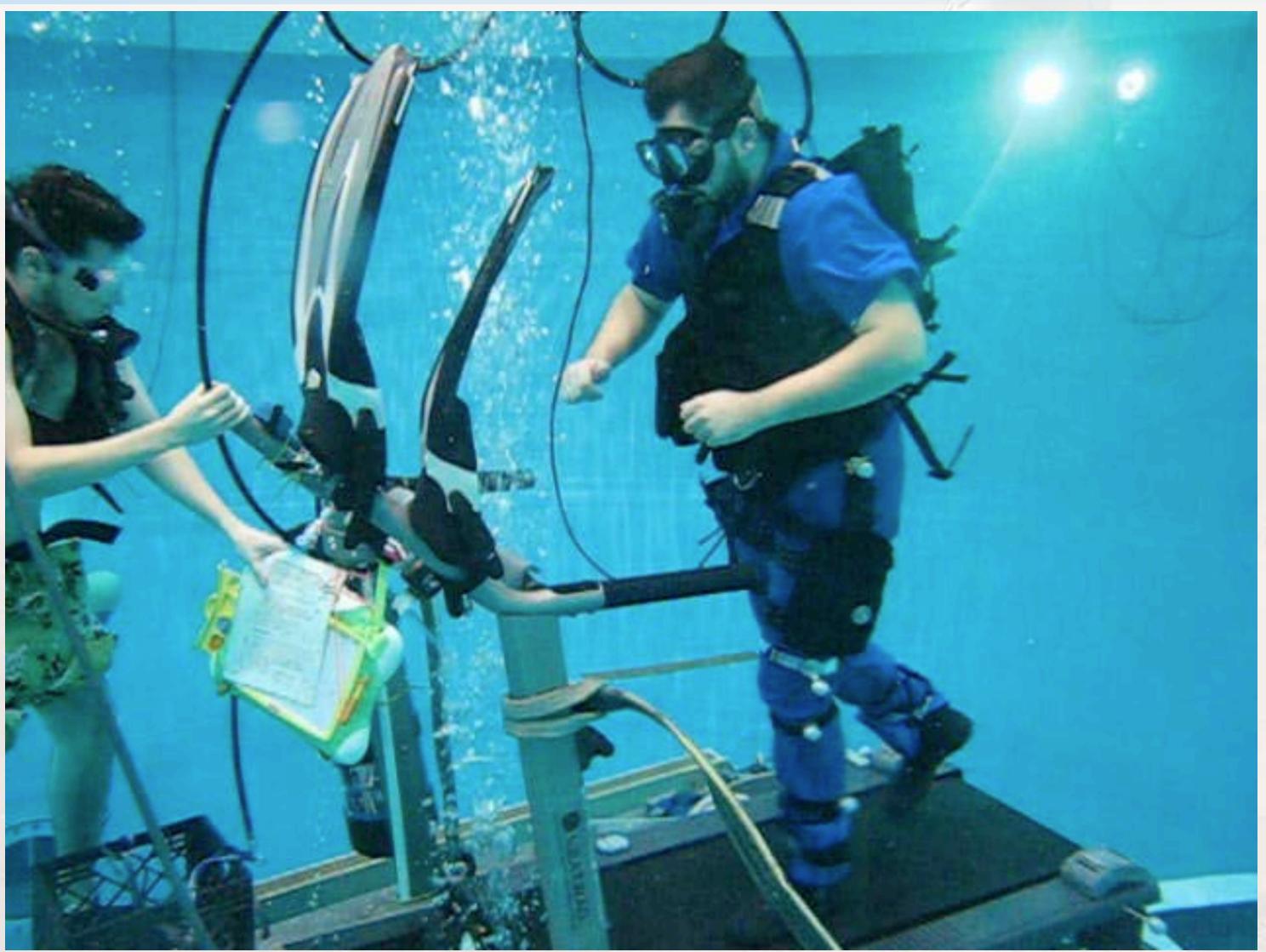
## Lunar Gravity - Slow Speed







## Lunar Gravity - High Speed





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## Earth Gravity - High Speed

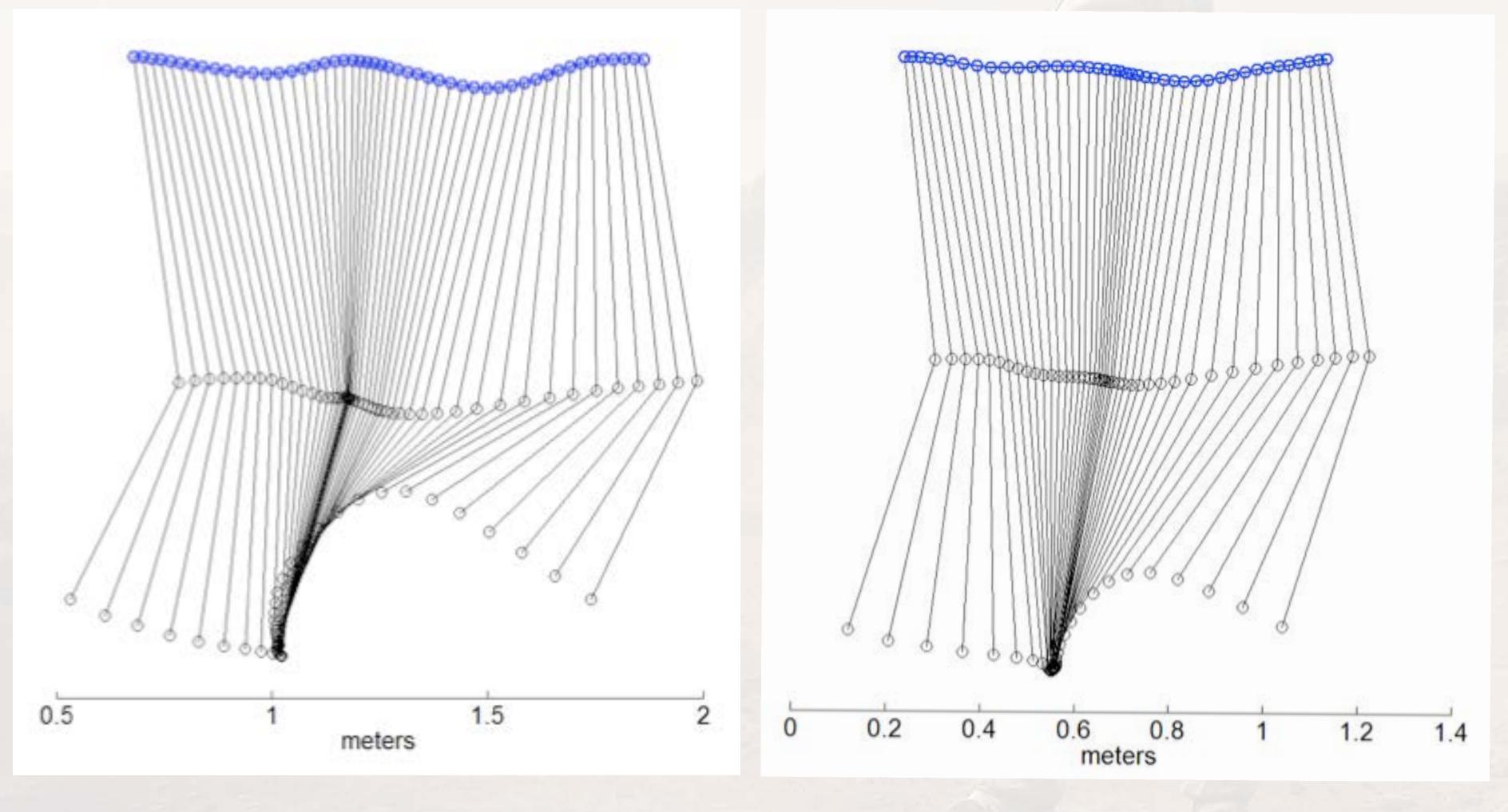




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## **Comparison of 1-G Leg Motions**



## Underwater

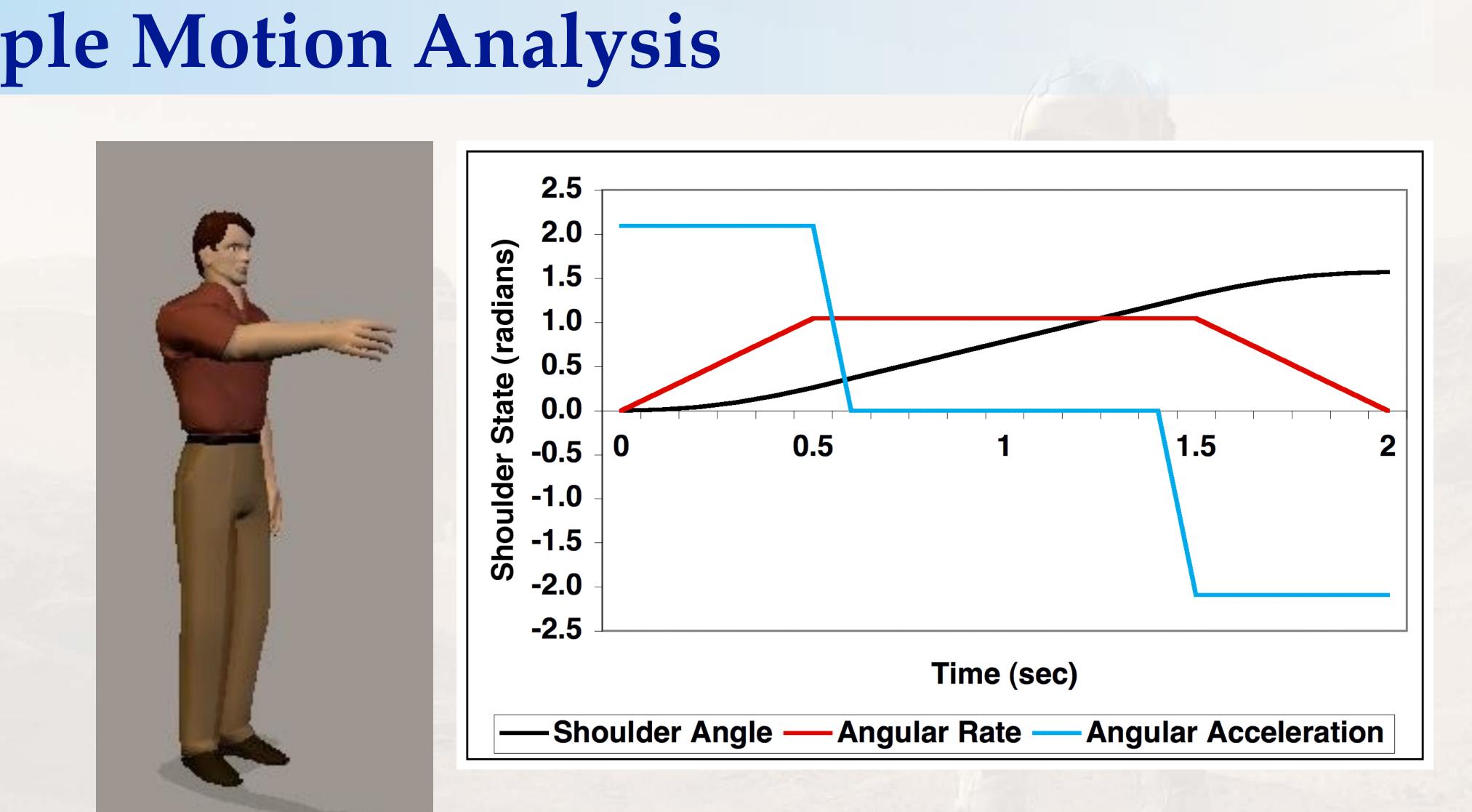


## Laboratory

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## **Sample Motion Analysis**

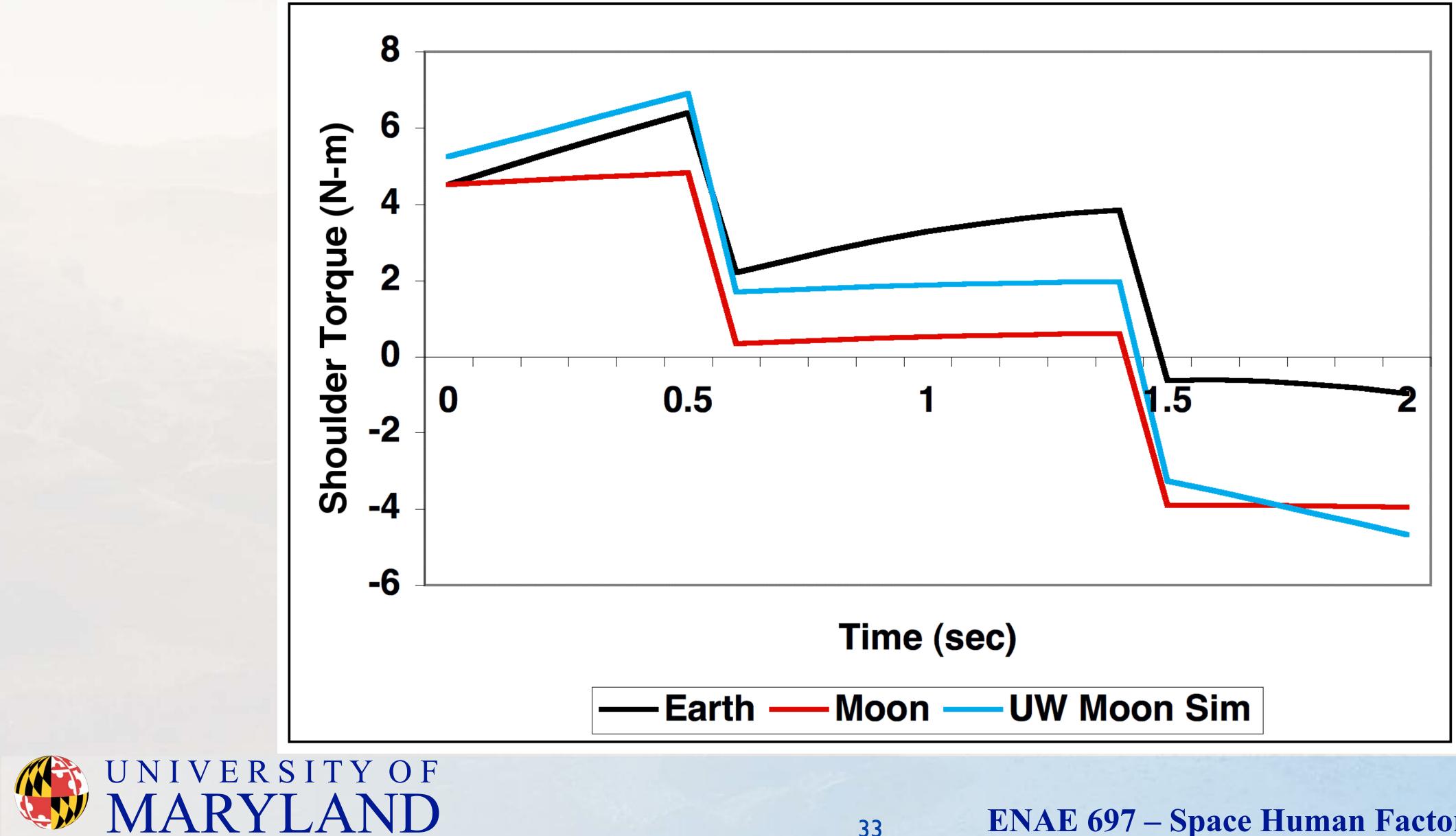


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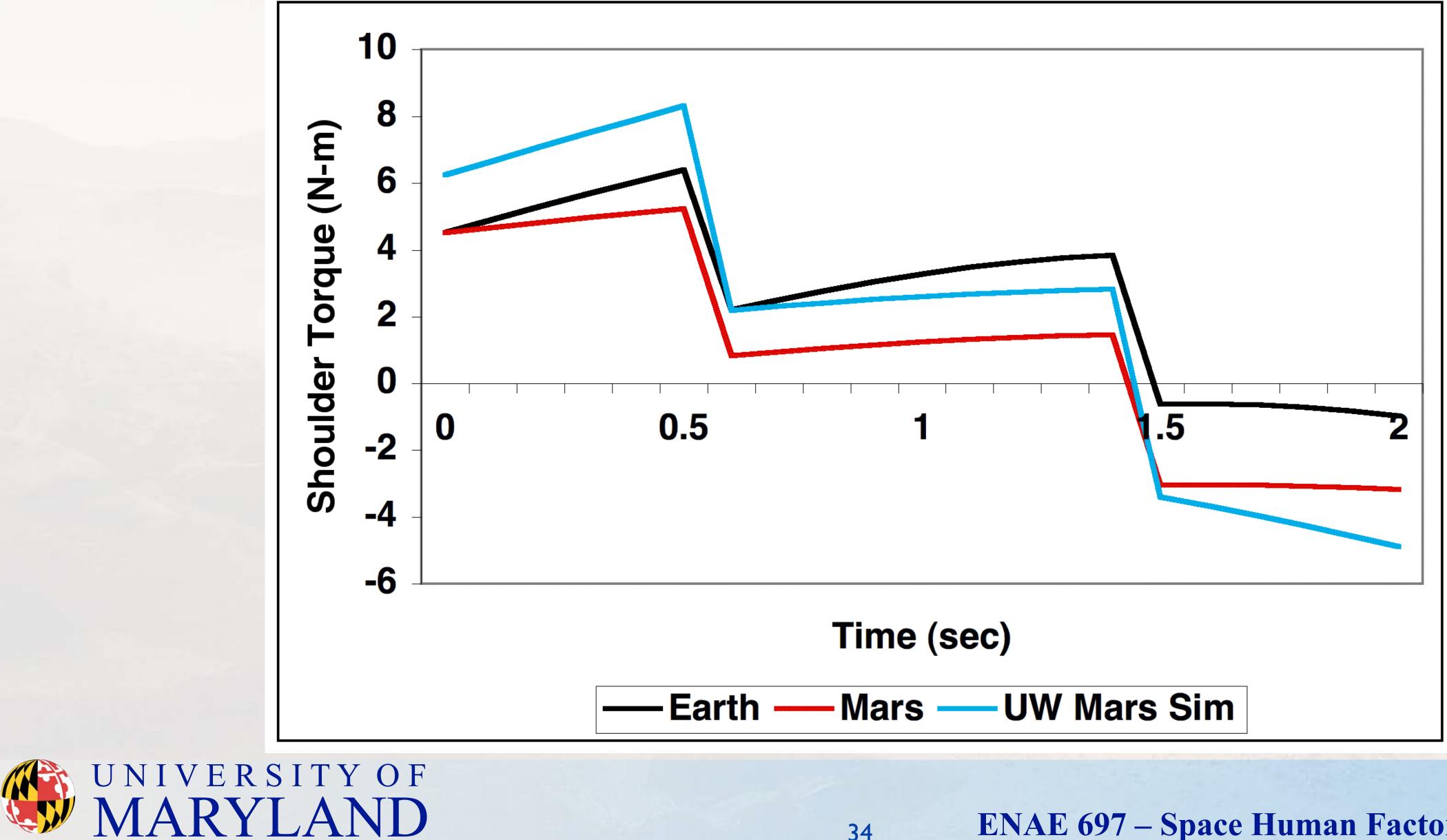
## **Effects of Lunar & Sim Environments**



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## **Effects of Mars & Sim Environments**



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## **Ballasted UW Simulation - Advantages**

- Simple arm torque analysis shows 52% reduction in RMS torque error compared to 1 g Lunar case; Mars error reduced by 9%
- Produces accurate levels of preload on legs
  - Sensorimotor control loops closer to actual partial gravity
  - Accurate simulation of postural responses

- Ability to work with test hardware of realistic mass and complexity • Freedom from wires or other simulation-specific interferences Realistic static and quasistatic test applications
  - Balance and postural studies
  - Reach and force envelopes
  - Surface sampling





## **Ballasted UW Simulation - Disadvantages**

- Dynamics effects of underwater environment
  - Water drag
  - Virtual mass
- Safety implications of underwater testing
  - Life support of test subject
  - Emergency extraction
- Access to pressure suits for EVA simulations



# • Requires added inertial mass to achieve desired counterweight

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## **Specialty Simulations**

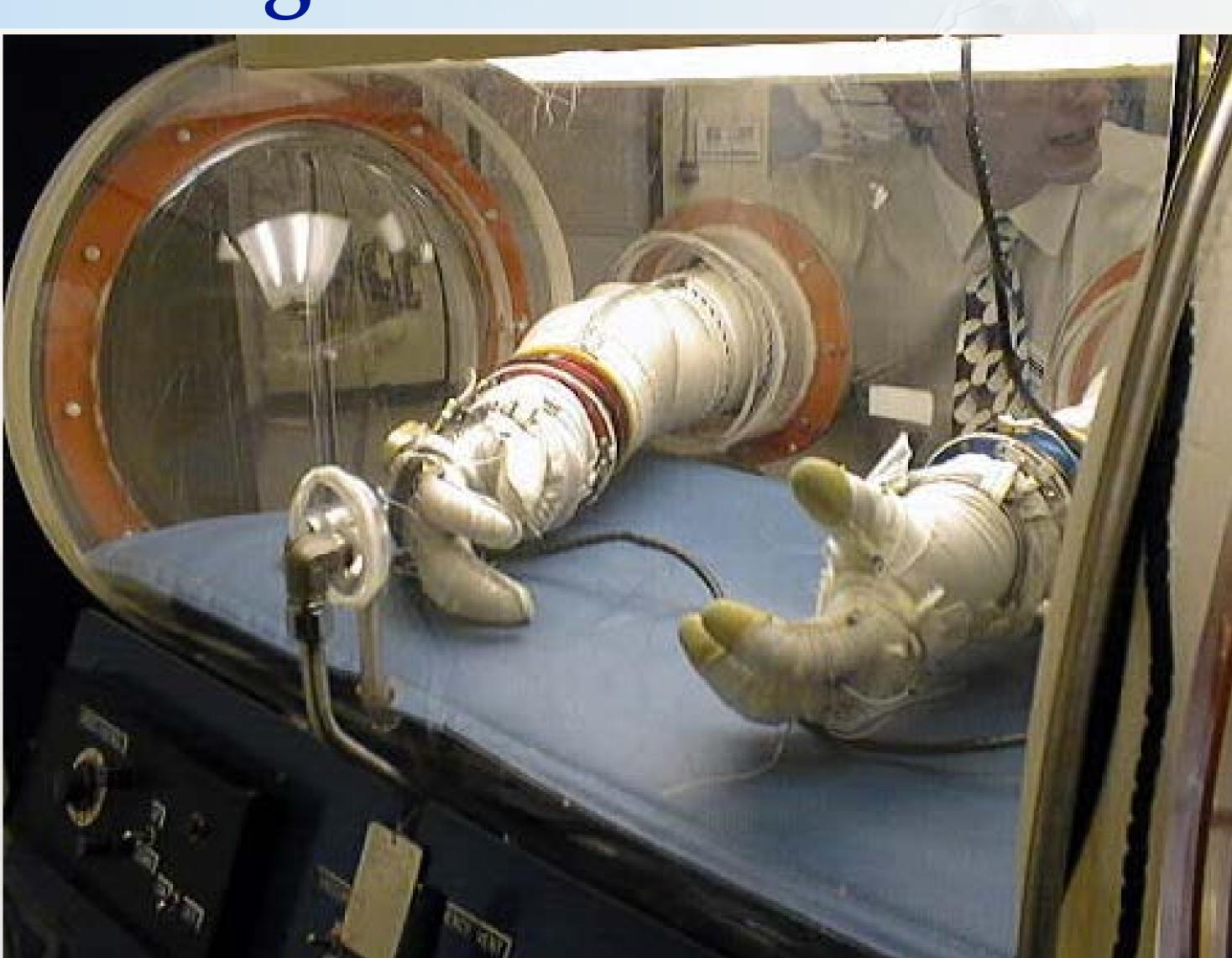
- Glove box testing
- Thermal vacuum testing
- Pressurized and unpressurized vehicles
- Habitat evaluation and habitability simulations



## zed vehicles tability simulations



## **Glove Box Testing**







## **TURTLE Pressurized Rover Sim 2008**







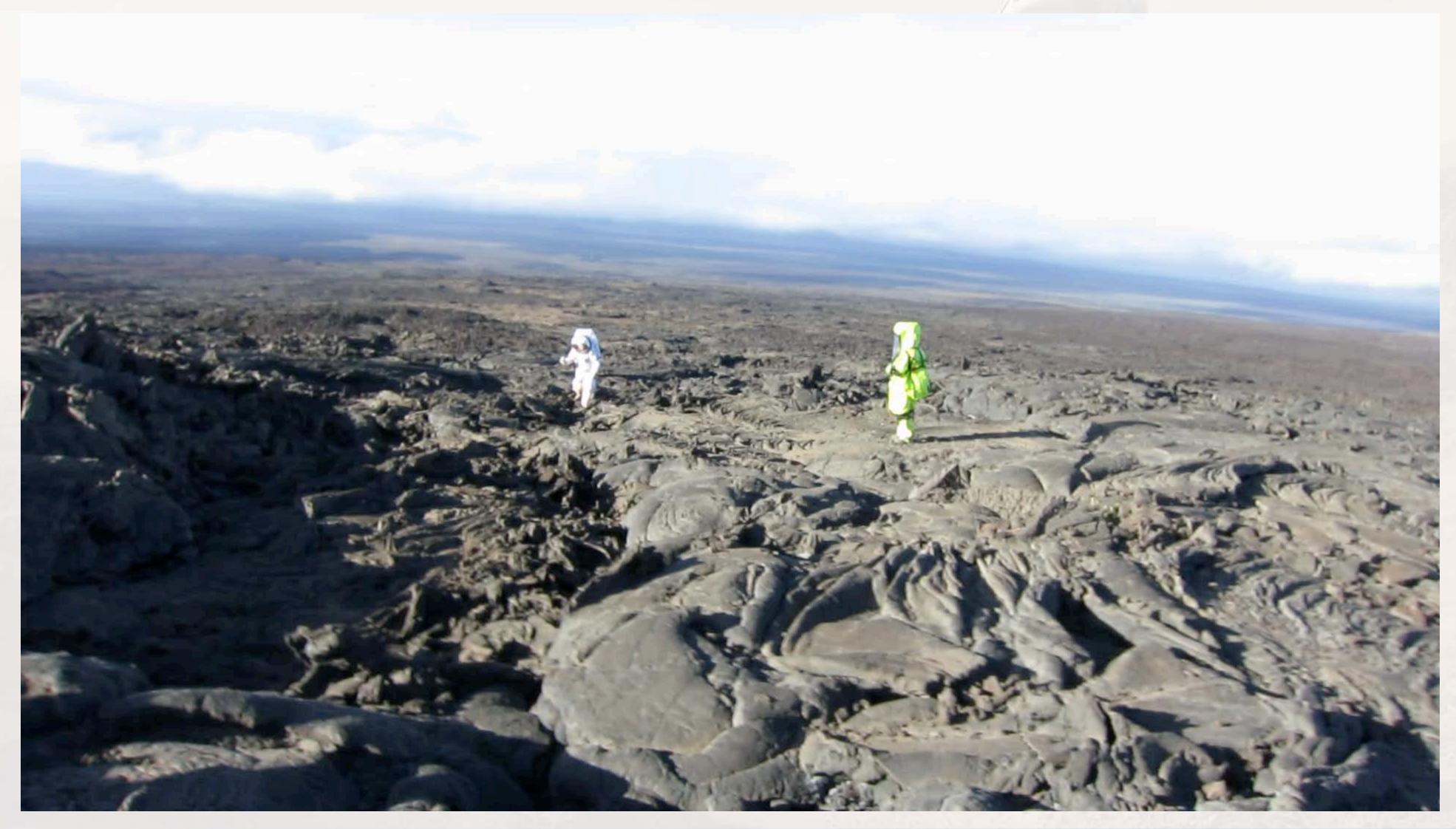
## **ECLIPSE Lunar Habitat Sim 2010**







## **HI-SEAS EVA Simulation**





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## Skylab Medical Experiments Altitude Test





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## **Extended-Duration Altitude Testing**







## **IVA Simulation - Mars 500**







## **Guidelines for Simulation Activities**

- Simulation is not an alternative to analysis!
- Use standard design analysis wherever feasible
- Simulation is appropriate for issues which are not amenable to analysis
  - Human in the loop control functions
  - Subjective assessments (e.g., habitability)
- status)
- Expensive in terms of both money and personnel time UNIVERSITY OF MARYLAND

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• Supports ancillary goals (e.g., outreach, publicity, competition

